

Correction of TOPEX/POSEIDON altimeter data for high frequency (2–20 days) barotropic motion in the East/Japan Sea

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Introduction (Previous Studies)



In a semi-enclosed sea,
Candela, J. (1991)

“The Gibraltar Strait and its role in the dynamics of the Mediterranean Sea”

Garrett and Majaess (1984)

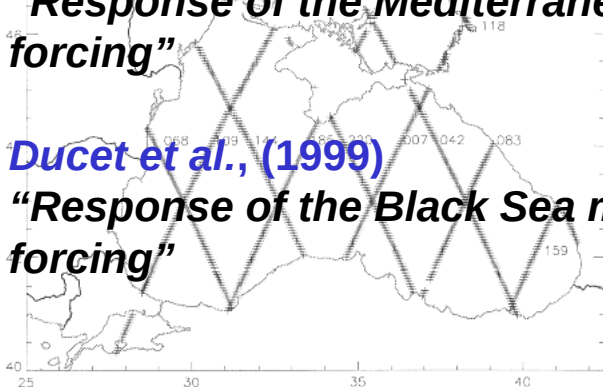
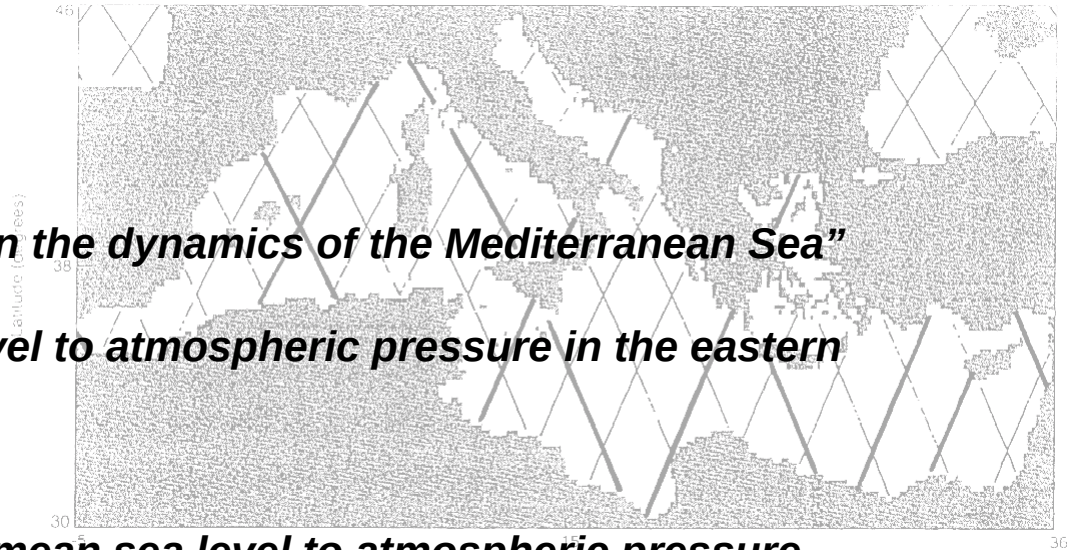
“Nonisostatic response of sea level to atmospheric pressure in the eastern Mediterranean”

Le Traon and Gauzelin (1997)

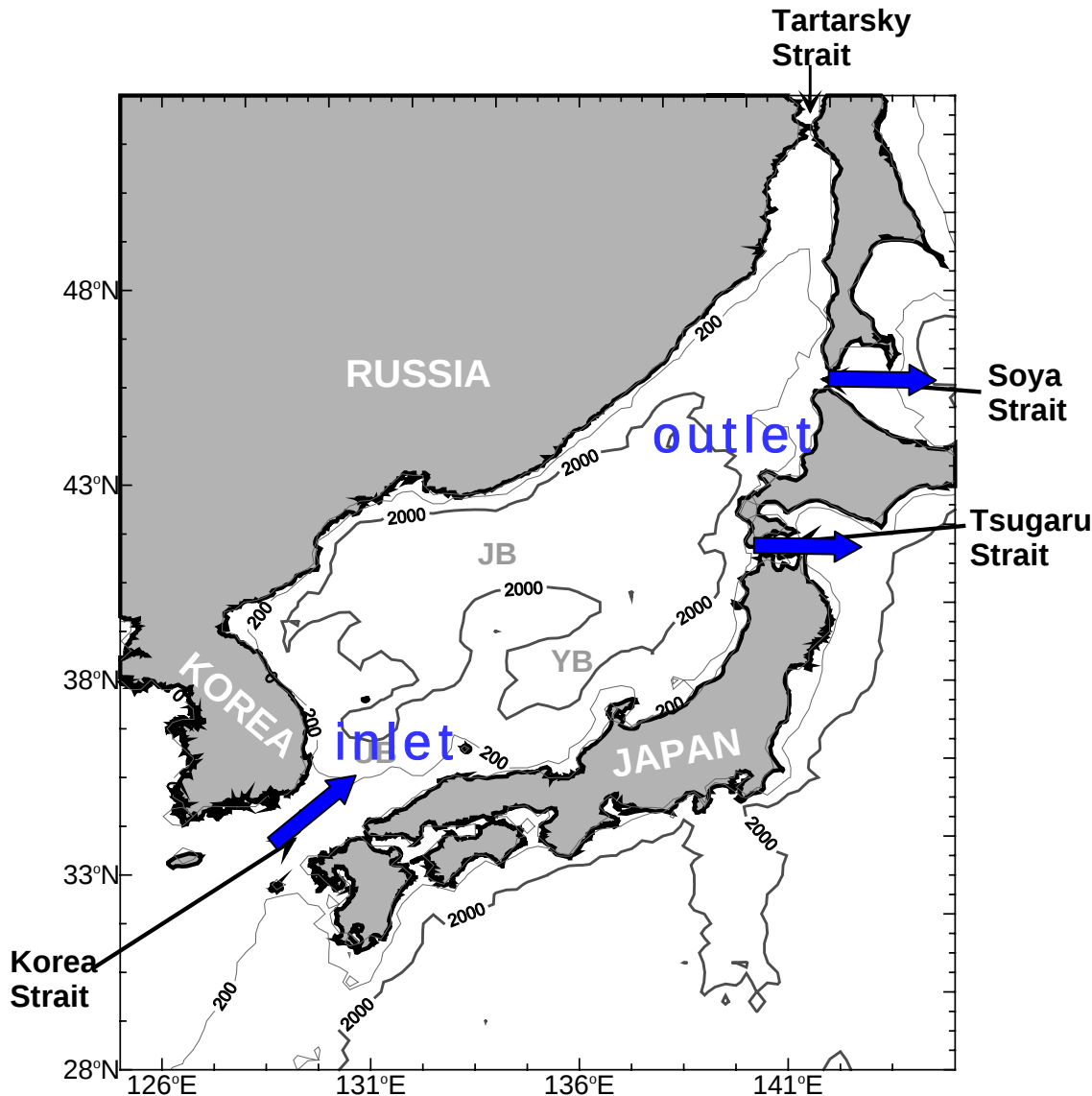
“Response of the Mediterranean mean sea level to atmospheric pressure forcing”

Ducet et al., (1999)

“Response of the Black Sea mean sea level to atmospheric pressure and wind forcing”



Introduction (East/Japan Sea)



Lyu et al. (2002)

“Atmospheric pressure-forced subinertial variation in the transport through the Korea Strait”

Park and Watts (2003)

“Response of Southwestern Japan/East Sea to atmospheric pressure”

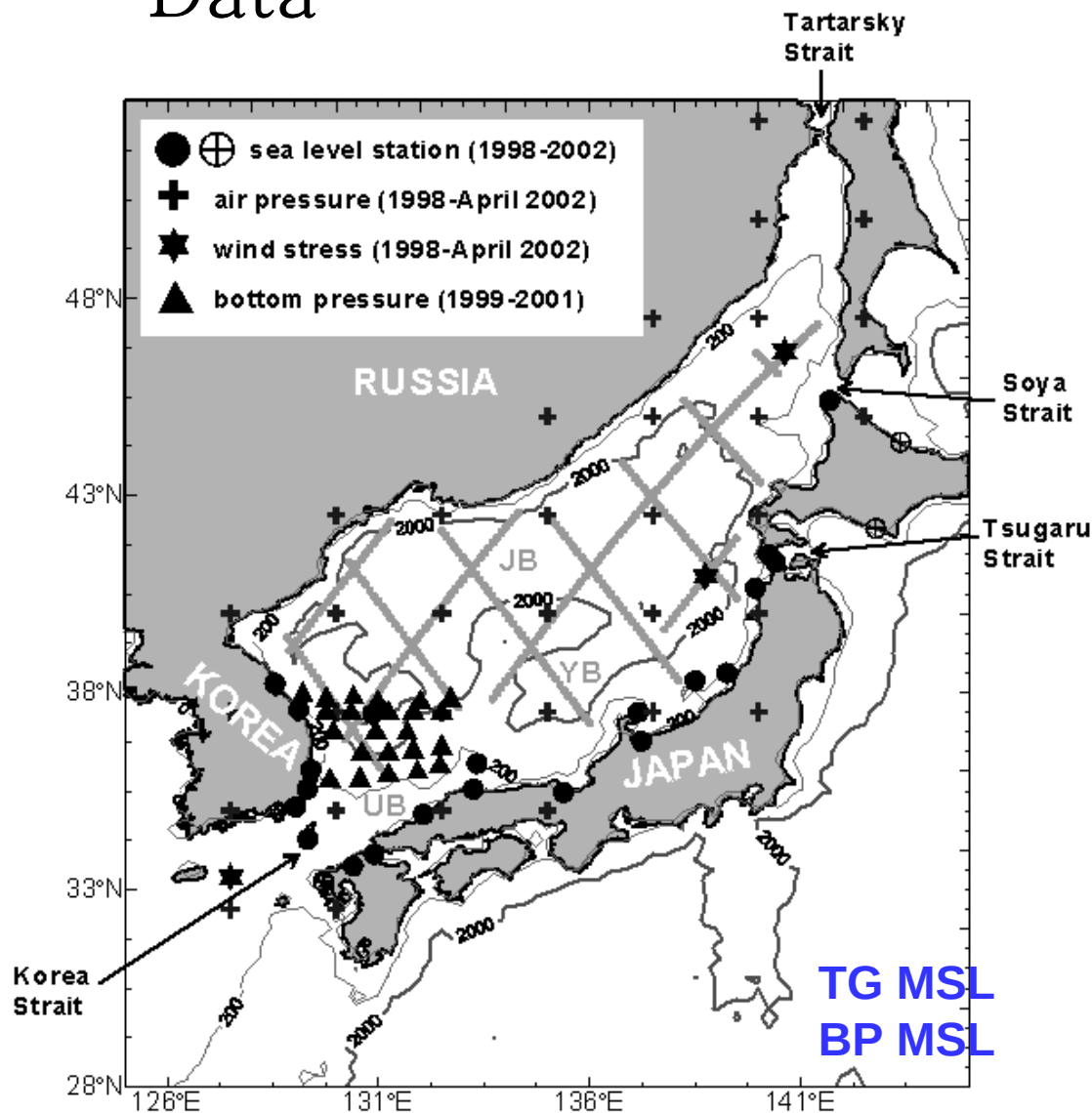
Lyu (2003)

“Temporal variation of the transport from the cable voltage across the Korea Strait and its mechanism”

Objective

- 1. To understand high frequency MSL fluctuation effects on the T/P data in the East/Japan Sea**
- 2. To provide an improved correction of the effects for the altimetry data with the Lyu model**

Data



Tide gauge (TG)

Spatially averaged sea level measured at 24 sites around and outside the East/Japan Sea

T/P altimeter

*JPL PO.DAAC (MGDR-B)
1998-2002 (cycle 180-375)*

Deep (> 1000 m) region

11 tracks in a cycle

Standard correction [Le Traon and Gauzelin, 1997]

Ocean tides are eliminated using the aliased harmonics [Morimoto et al., 2000]

NCEP

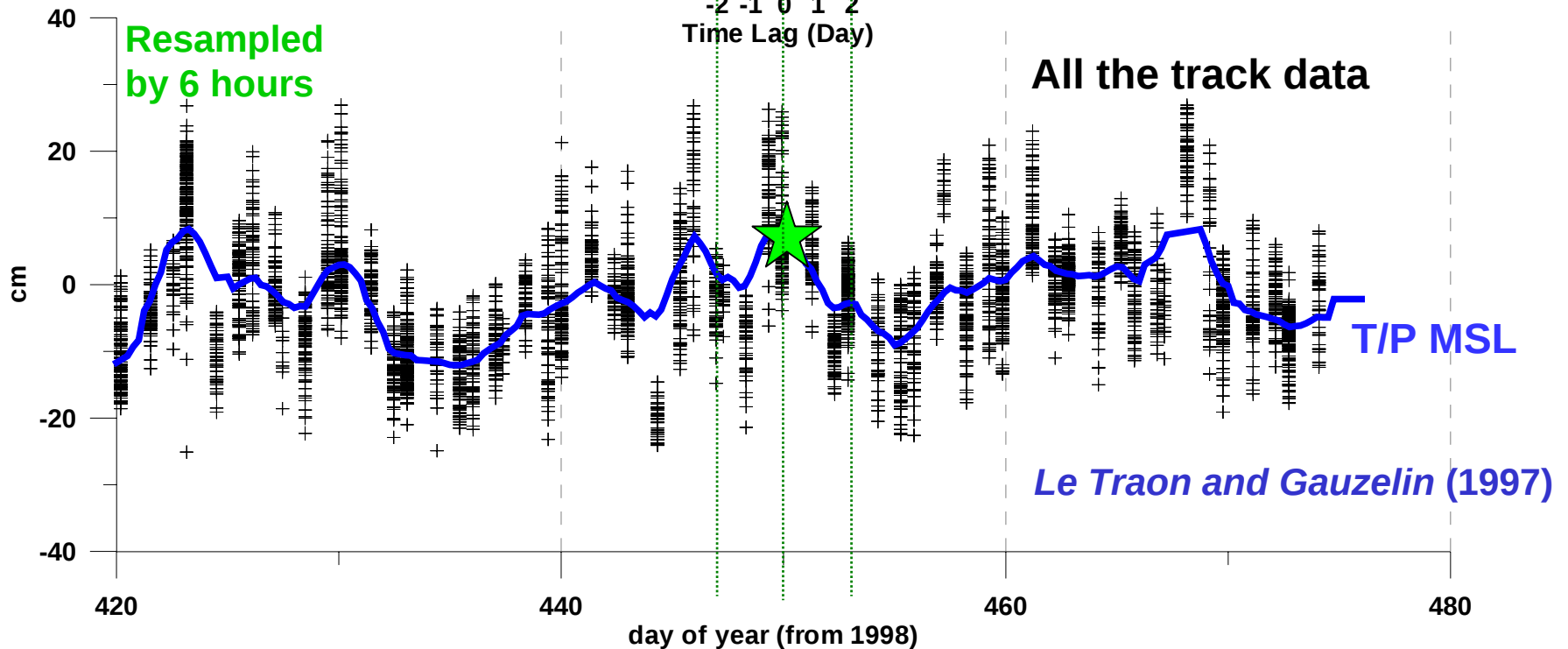
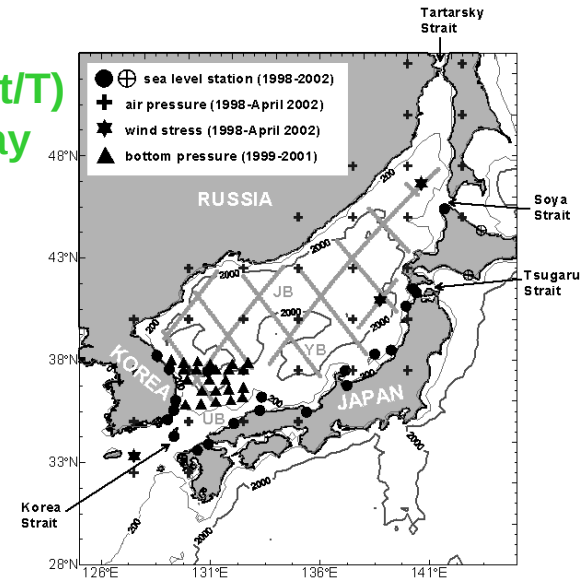
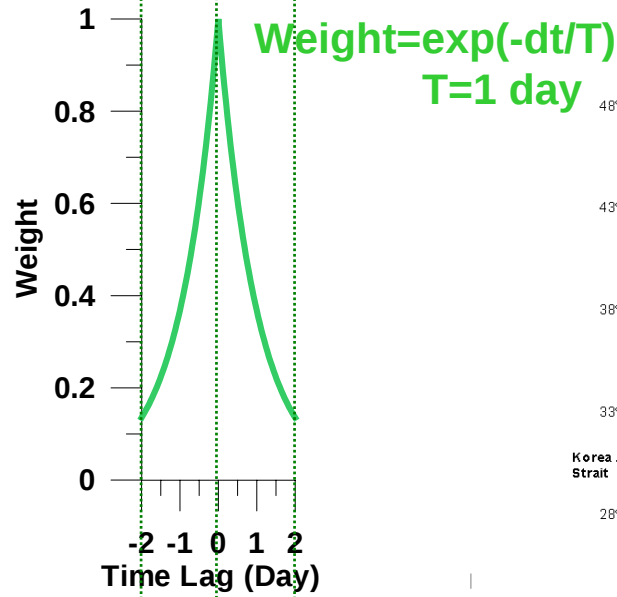
reanalyzed data

*Spatially averaged air pressure
Wind stresses on the straits*

Bottom pressure (BP)

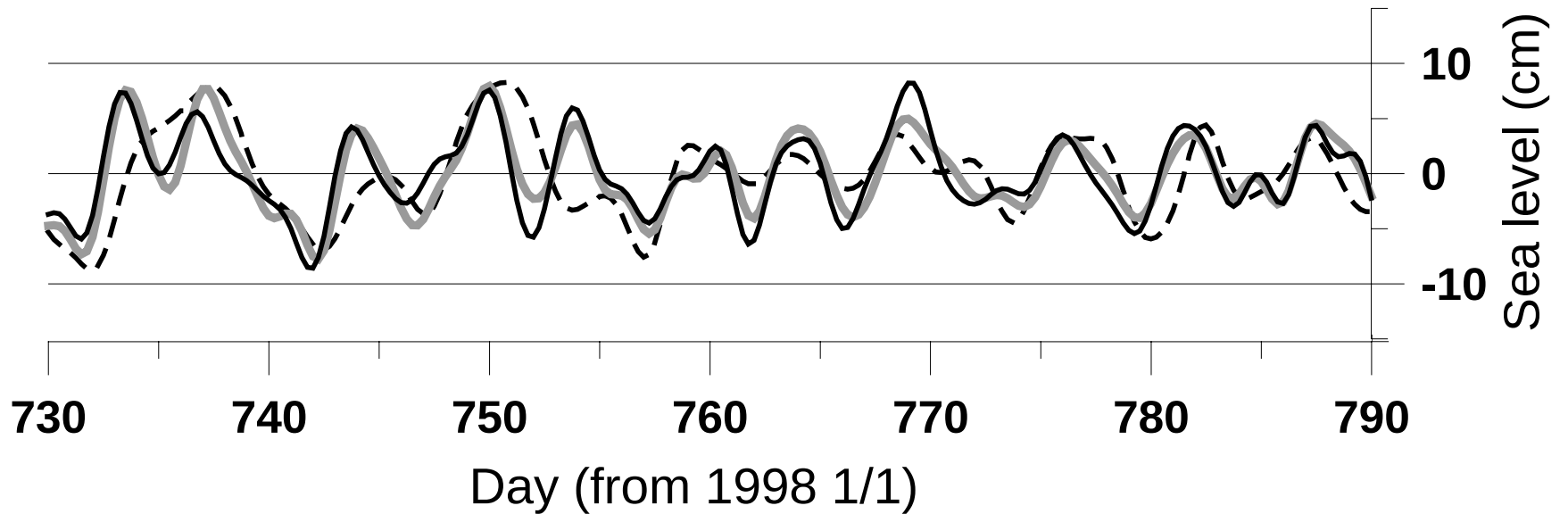
Spatially averaged bottom pressure measured at 23 sites in the Ulleung Basin

Data (T/P MSL)



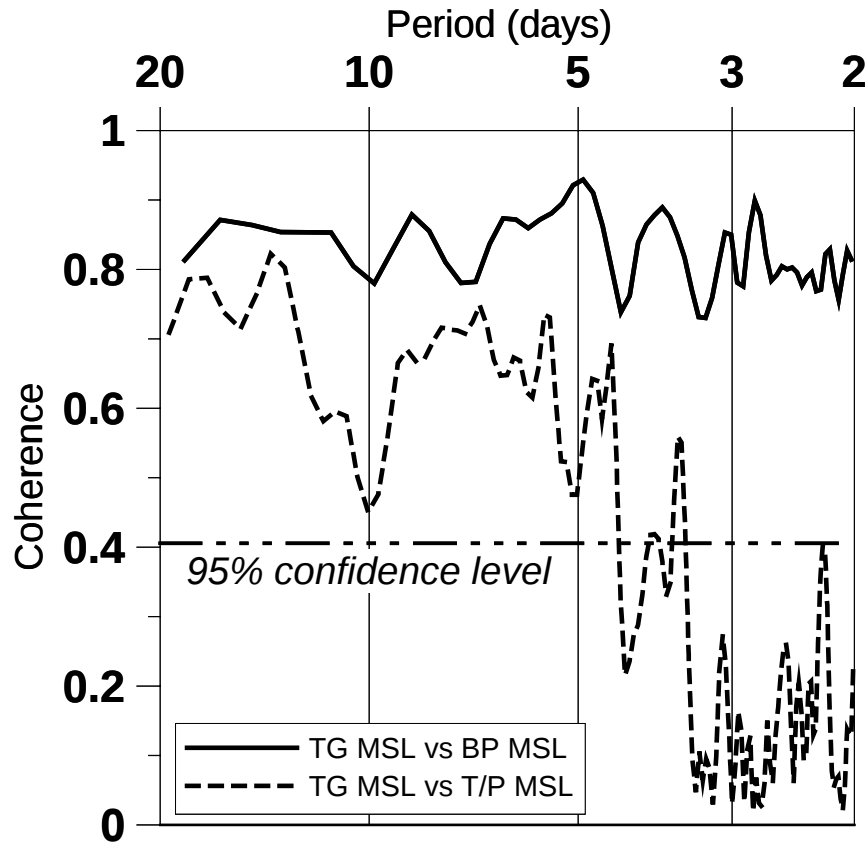
Results (Time Series Analysis)

— TG MSL
- - - T/P MSL
— BP MSL

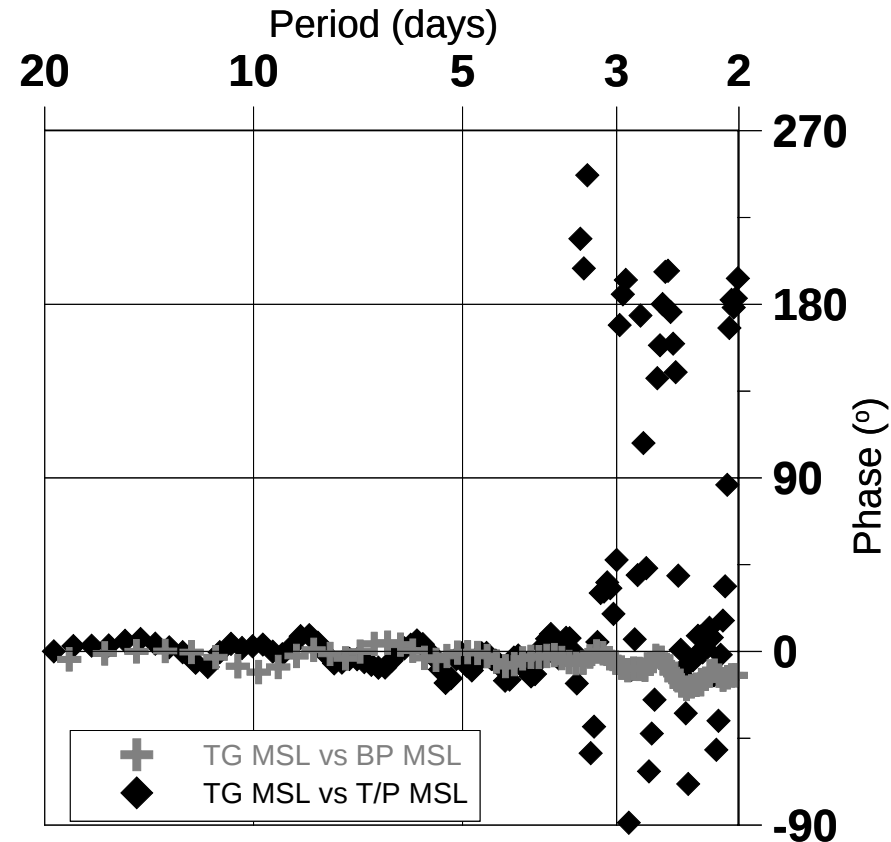


Results (Cross-spectrum Analysis)

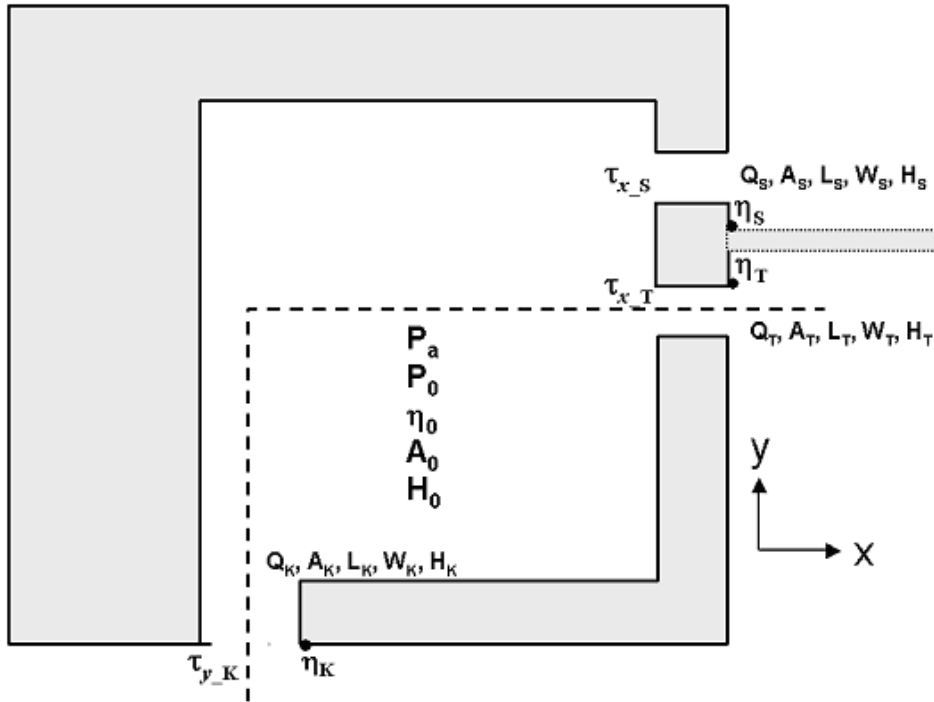
Coherence



Phase



Application of Lyu model (1)



Lyu model equations

$$\begin{aligned} \frac{\partial Q_{K,T,S}}{\partial t} = & -\frac{A_{K,T,S}}{\rho} \left(\frac{\partial P}{\partial x}, \frac{\partial P}{\partial y} \right) \\ & + \frac{A_{K,T,S}}{\rho H_{K,T,S}} \tau_{K,T,S} - \lambda_{K,T,S} Q_{K,T,S} \end{aligned}$$

$$A_0 \frac{\partial \eta_0}{\partial t} = Q_K - Q_T - Q_S,$$

$$P_0 = P_a + \rho g \eta_0$$

Lyu et al. (2002)

Lyu (2003)

Application of Lyu model (2)

Lyu model solutions

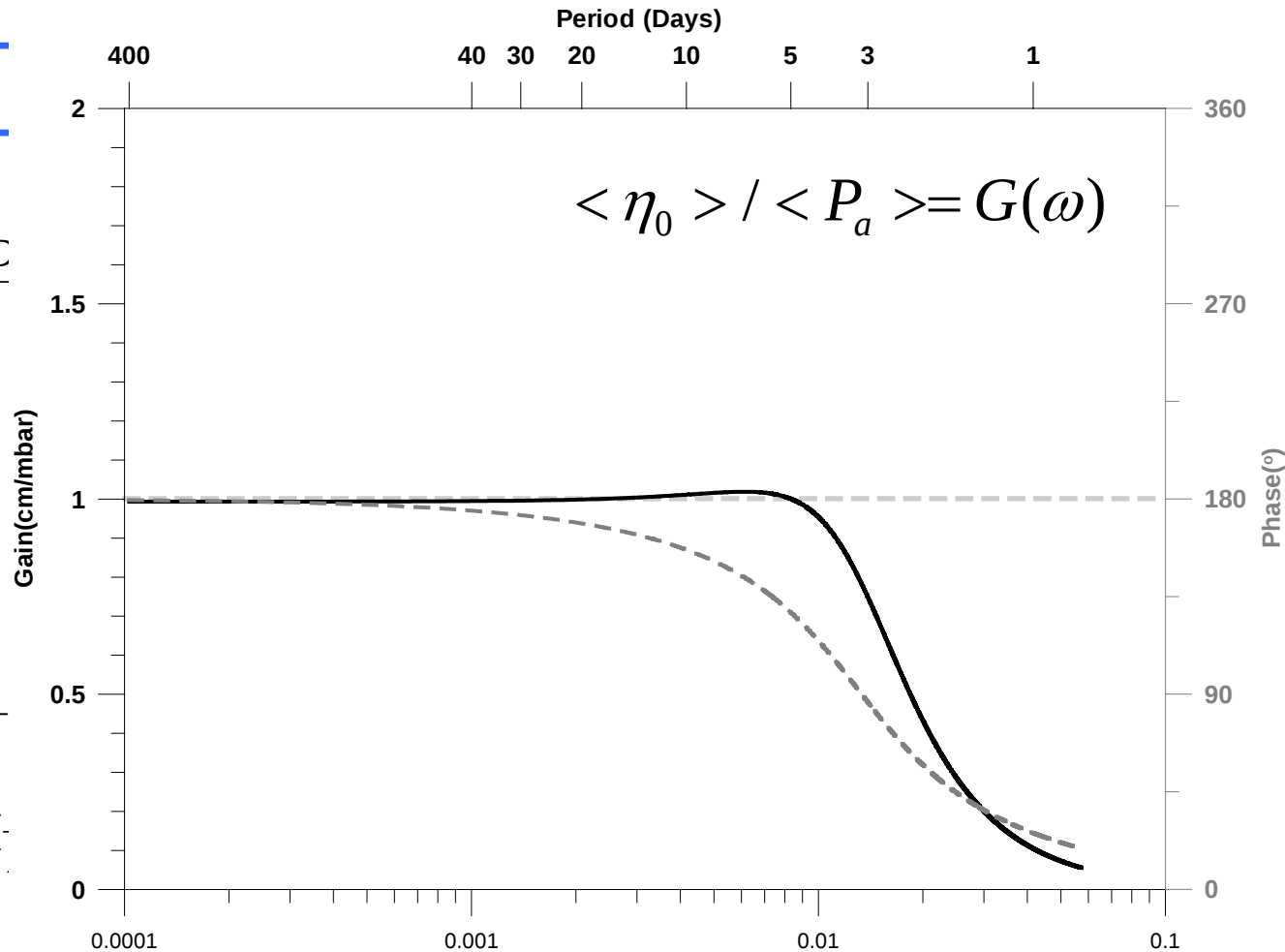
$$\eta_0 = \frac{[\{D_r(Q_{Ki} - Q_{Ti} - Q_{Si}) - L$$

$$Q_{(K,T,S)} = Q_{(Kr,Tr,Sr)} + Q_{(Ki,Ti,Si)}$$

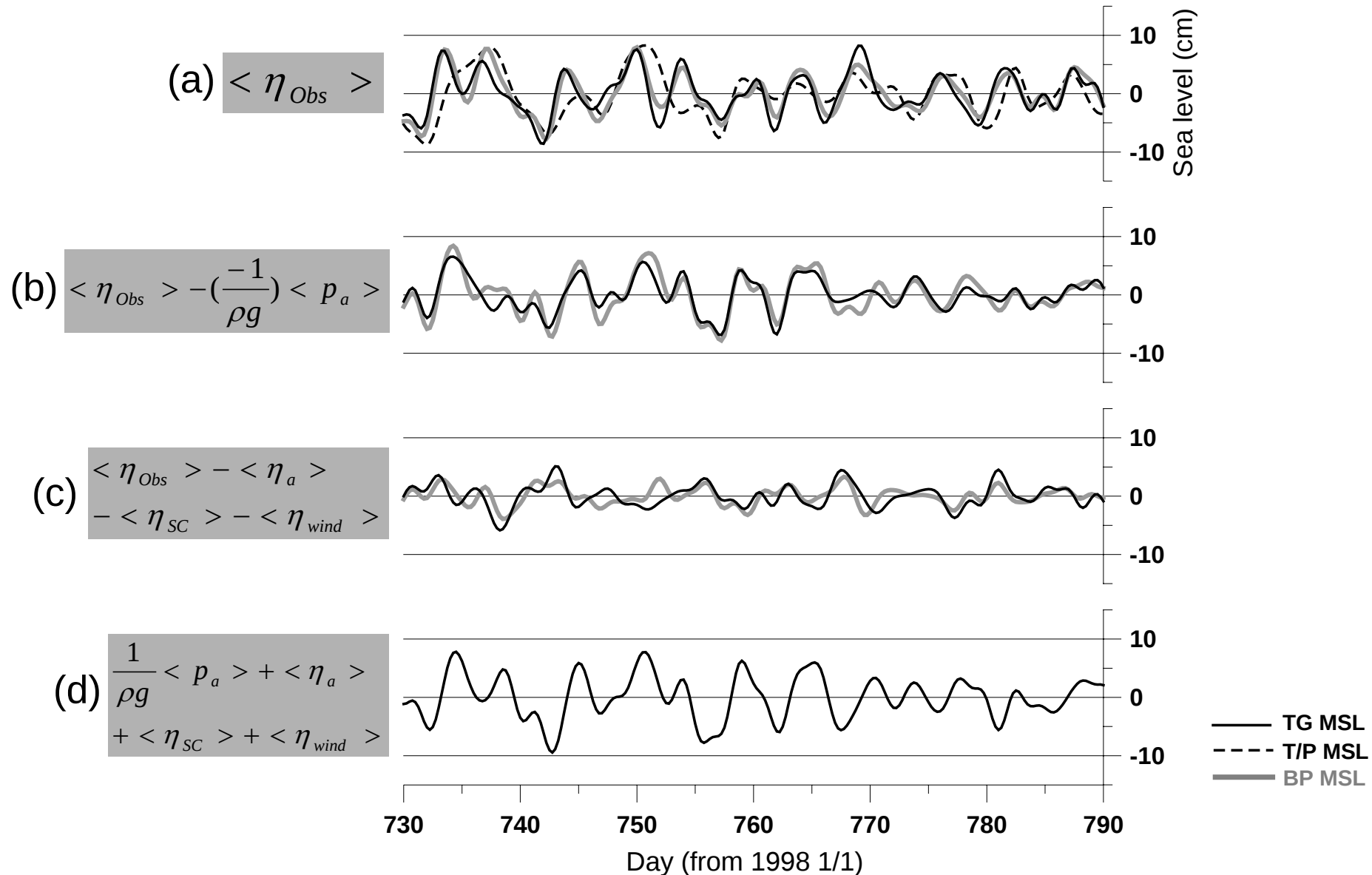
$$D = D_r + iD_i$$

$$= [-\omega^2 \{ \omega^4 - (\frac{gA_K}{AL_K} + \frac{gA_T}{AL_T} +$$

$$+ i[\omega^3 \{ (\lambda_K + \lambda_T + \lambda_S) \omega^2 - ($$



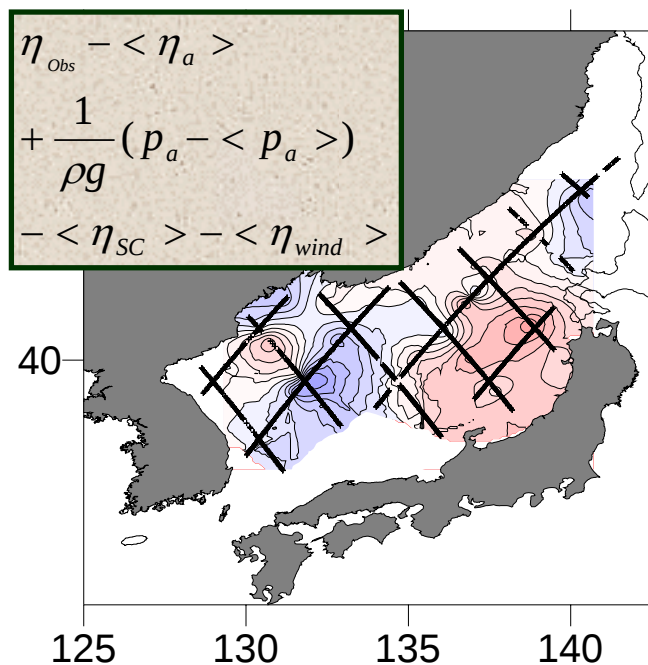
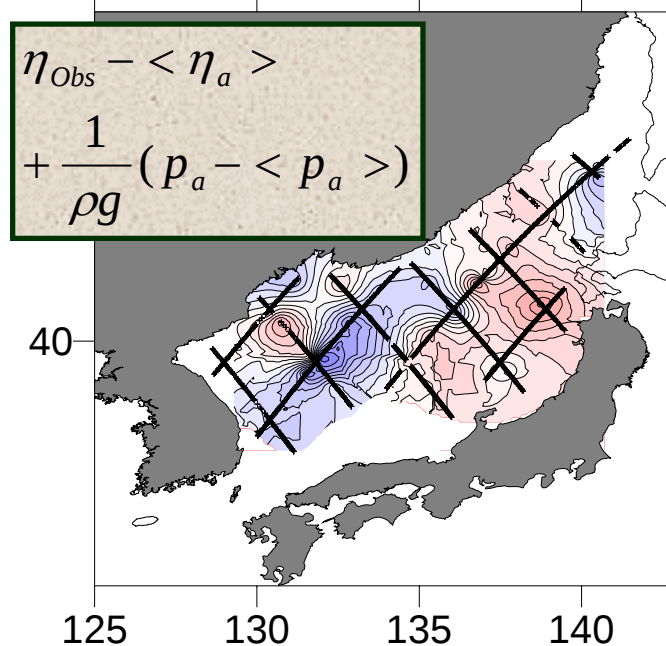
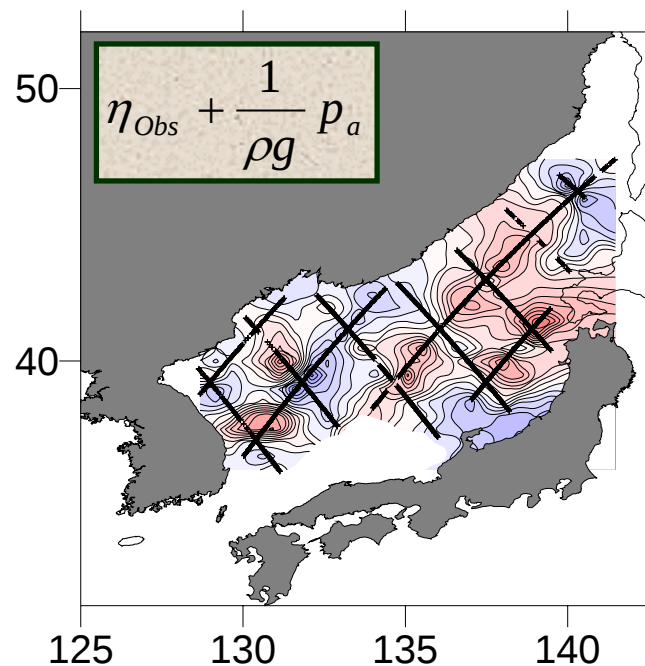
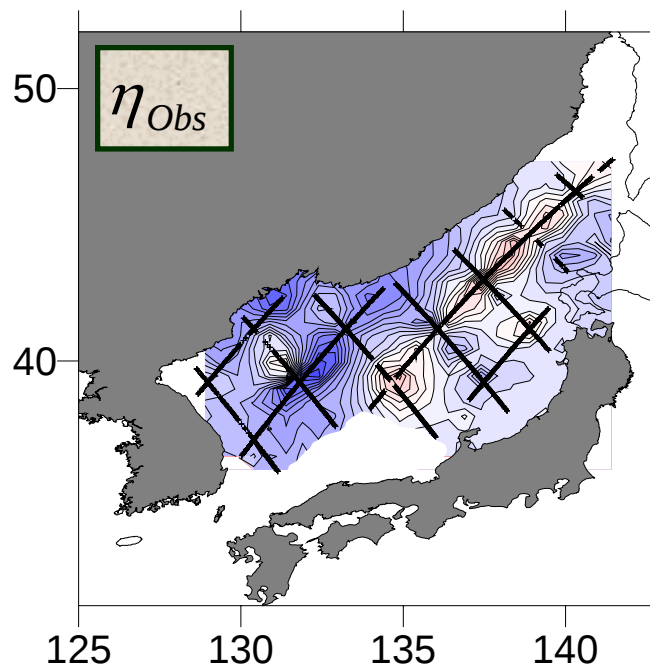
Lyu model Impact (Time Series)



Lyu model Impact (Table)

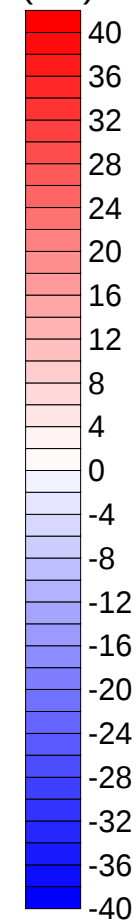
	Variance (cm ²)	
	TG MSL	BP MSL
1. $\langle \eta_{Obs} \rangle$	19.0	21.2
2. $\langle \eta_a \rangle$	13.2	
3. $(-1/\rho g) \langle p_a \rangle$	14.2	
4. $\langle \eta_a \rangle - (-1/\rho g) \langle p_a \rangle$	7.7	
5. $\langle \eta_{Obs} \rangle - (-1/\rho g) \langle p_a \rangle$	11.1	11.0
6. $\langle \eta_{Obs} \rangle - \langle \eta_a \rangle$	9.2	9.6
7. $\langle \eta_{Obs} \rangle - \langle \eta_a \rangle - \langle \eta_{SC} \rangle$	6.7	4.9
8. $\langle \eta_{Obs} \rangle - \langle \eta_a \rangle - \langle \eta_{SC} \rangle - \langle \eta_{wind} \rangle$	5.7	3.9
9. $\langle \eta_a \rangle + \langle \eta_{SC} \rangle + \langle \eta_{wind} \rangle - (-1/\rho g) \langle p_a \rangle$	12.3	

Latitude (°N)



10 days mapping
during the day of
750-760 (winter)

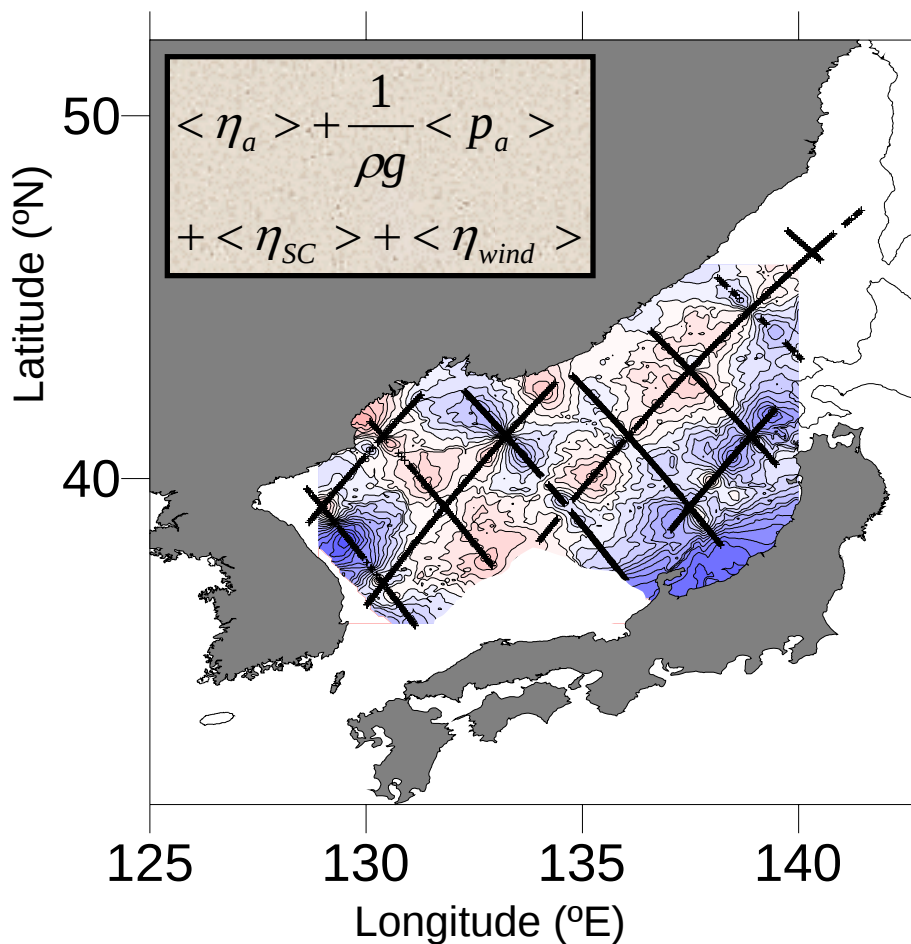
sea level
(cm)



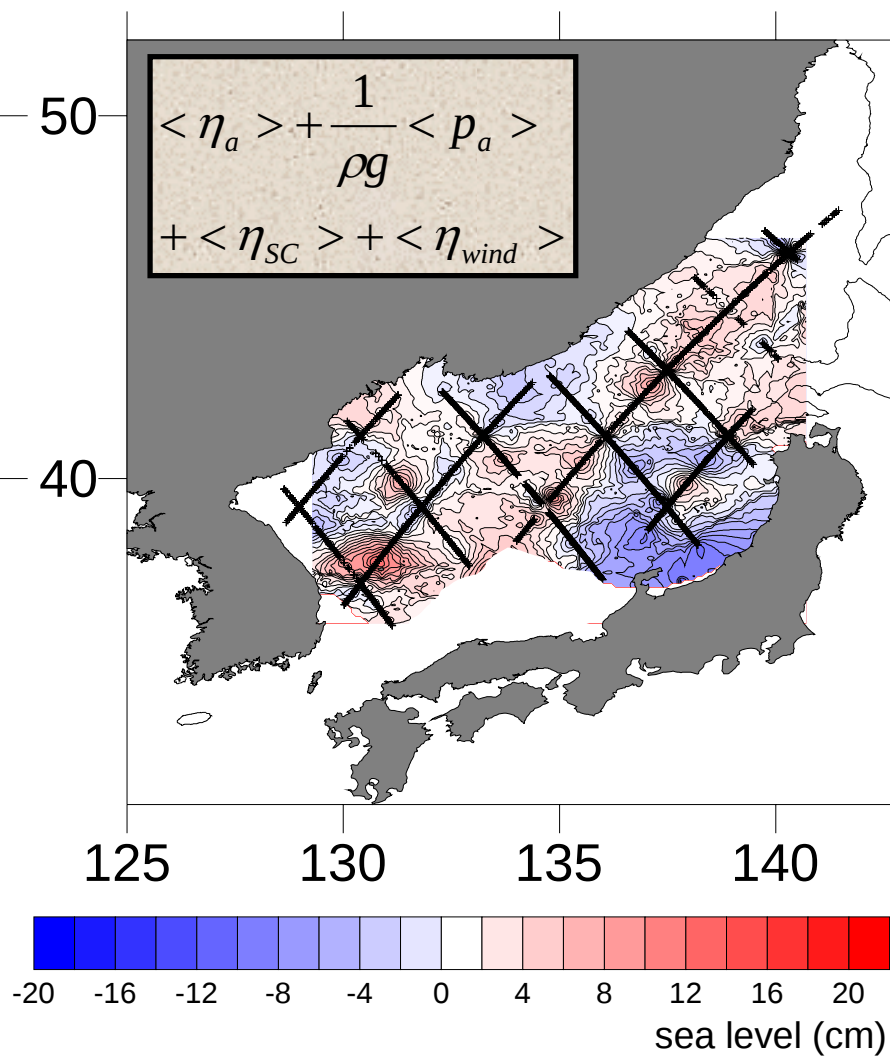
Longitude (°E)

10 Day Contour Map (Difference)

10 days mapping
during the day of 580-590 (summer)



10 days mapping
during the day of 750-760 (winter)



Conclusion

- The Lyu (analytic) model
 - ➔ significantly improved correction of high-frequency (2-20 days) sea level fluctuation effects on satellite altimeter data, compared to the standard IB correction
- Rms difference of 3-4 cm between the model and IB corrections with maximum difference of up to 10 cm
 - ➔ the impact on the two-dimensional mapping of SSH is substantial
- Most (70-80%) of the high frequency variances in the TG MSL and BP MSL
 - ➔ explained by the Lyu model
- Trackiness in the 10 day T/P maps of SSH with no correction or only with IB correction
 - ➔ significantly improved with the model correction

Thank You !

Discussion

- **Not used T/P MSL in the East Sea**
- **TG data limitation in representing East Sea MSL (coastal effects or errors due to unevenly distributed TG stations)**
- **BP MSL measured only in the Ulleung Basin, not the entire East Sea (comparison between Ulleung Basin mean bottom pressure and East Sea mean bottom pressure)**
- **Lyu model limitation**
- **Some cycles for which the model correction does no better than the IB correction in reducing the high frequency fluctuations**
- **Tidal errors**

Future Studies

Numerical model

- ➔ complex bathymetry of the straits and the three (Japan, Yamato, and Ulleung) basins in the East Sea
- ➔ baroclinic part of the fluctuations
- ➔ variations of the internal structures inside the East Sea
- ➔ roles of external forcings from the East China Sea, Yellow Sea, Okhotsk Sea, and Northeastern Pacific.

Merging multiple-satellite altimeter mission *(T/P+ERS+ENVISAT+Jason-1)*

- ➔ significant improvement for spatial mapping. *[Le Traon and Gauzelin, 2000]*

Formulation (Sea level decomposition)

Subsurface pressure

$$p = \rho g \eta_{Obs} + p_a = \rho g \eta_{Obs} + \langle p_a \rangle + (p_a - \langle p_a \rangle) \\ = \rho g \eta'$$

Adjusted sea level

$$\eta' = \left\{ \eta_{Obs} + \frac{1}{\rho g} \langle p_a \rangle + \frac{1}{\rho g} (p_a - \langle p_a \rangle) \right\} \\ = \left\{ \langle \eta_a \rangle + \frac{1}{\rho g} \langle p_a \rangle \right\} + \langle \eta_{SC} \rangle + \langle \eta_{wind} \rangle + \eta_{residual}$$

Observed sea level

$$\eta_{Obs} = \langle \eta_a \rangle - \frac{1}{\rho g} (p_a - \langle p_a \rangle) + \langle \eta_{SC} \rangle + \langle \eta_{wind} \rangle + \eta_{residual}$$

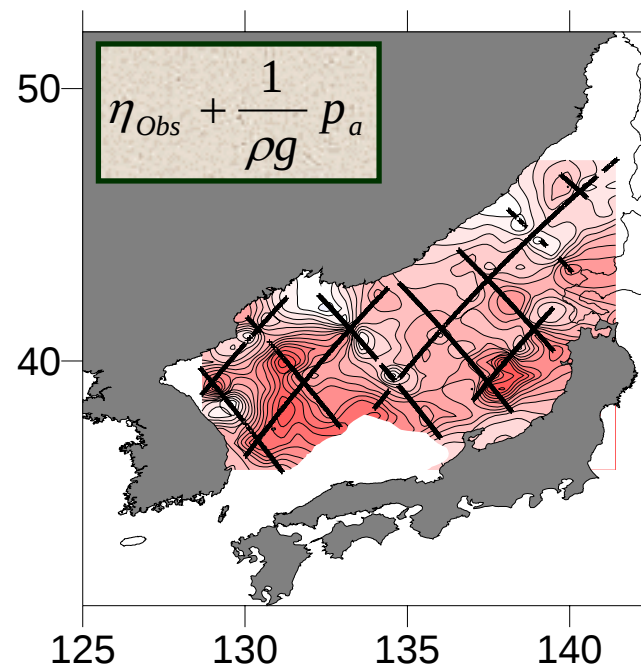
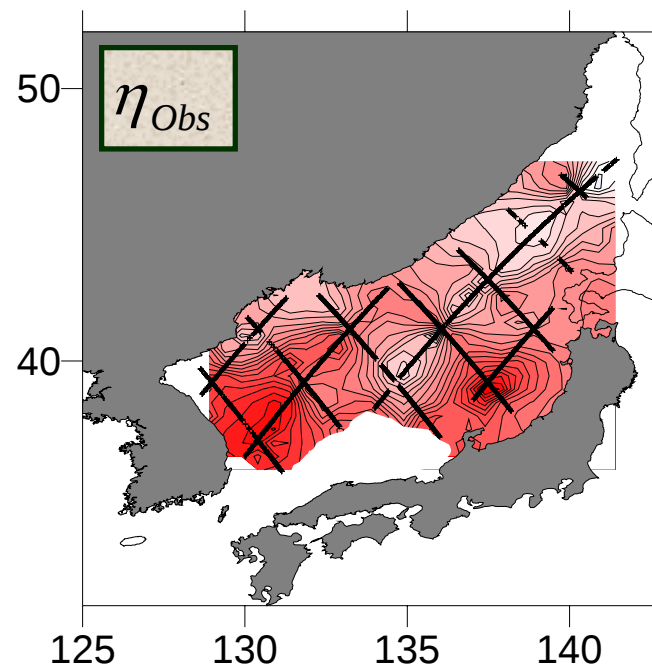
Model output

Observed MSL

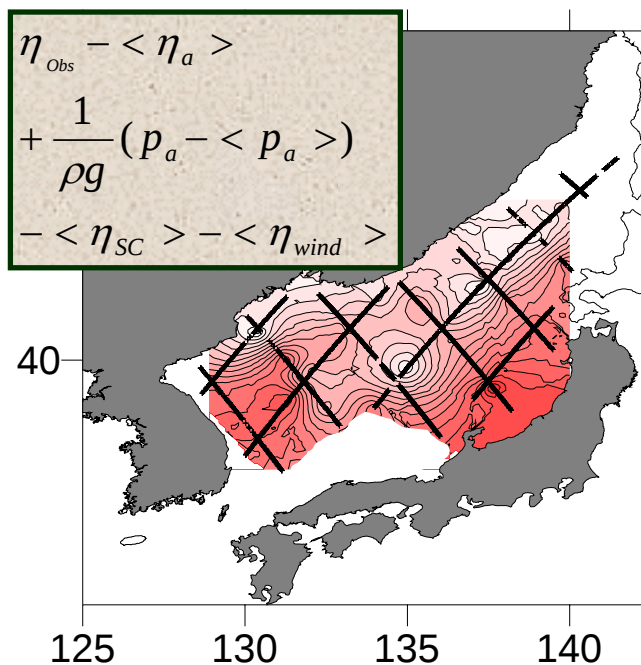
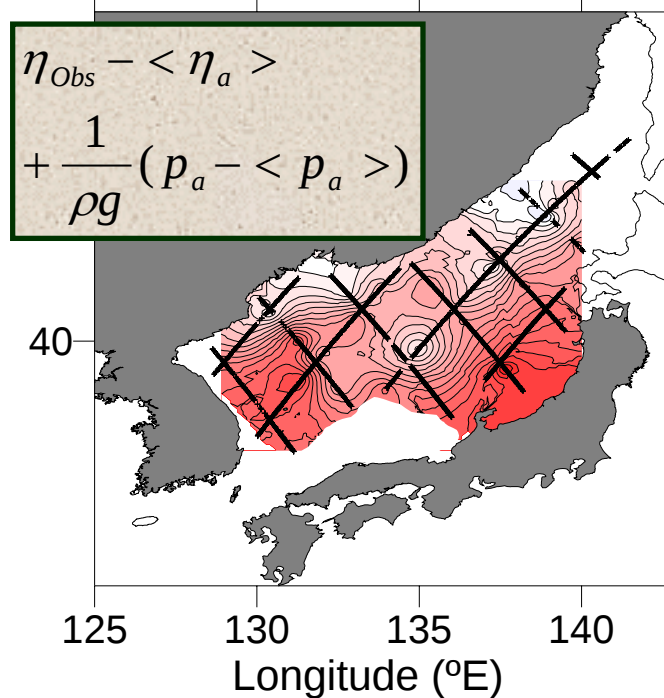
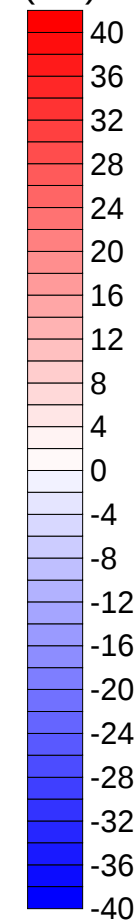
$$\langle \eta_{Obs} \rangle = \langle \eta_a \rangle + \langle \eta_{SC} \rangle + \langle \eta_{wind} \rangle + \langle \eta_{residual} \rangle$$

10 days mapping
during the day of
580-590 (summer)

Latitude (°N)



sea level
(cm)



Longitude (°E)

