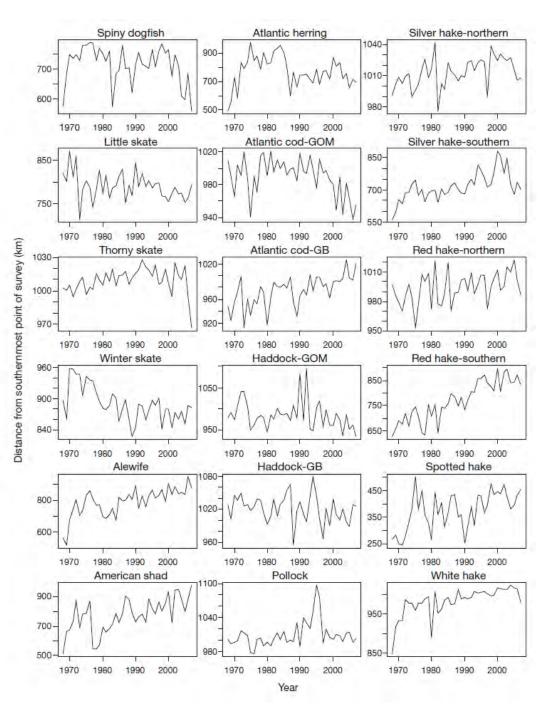
Predicting marine ecosystem responses to environmental variation: *Now is the time to merge bioenergetics and movement ecology*

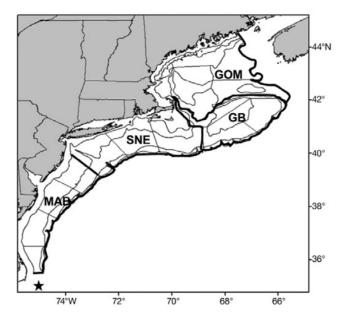
Kenneth Rose Horn Point Laboratory Cambridge, Maryland



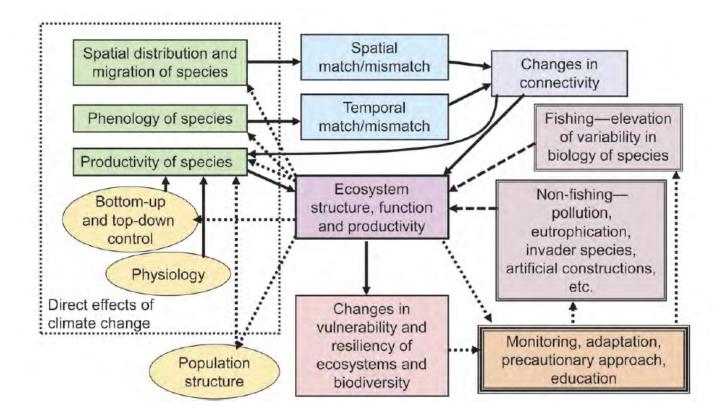
Today

- Organisms will move in response to climate change
- Progress on movement
 - Observations
 - Modeling
- Status of bioenergetics
- Need and opportunities for merging
- Next steps





Nye et al. 2009. Marine Ecology Progress Series 393: 111-129.₃

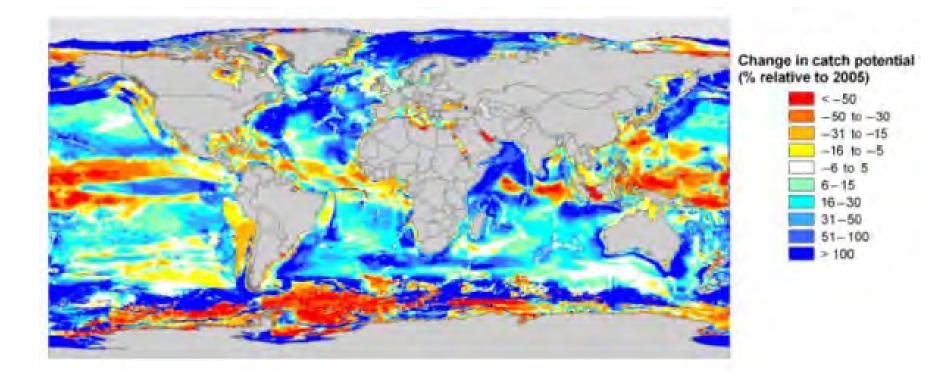


Hollowed et al. 2013. ICES Journal of Marine Science 70: 1023-1037.

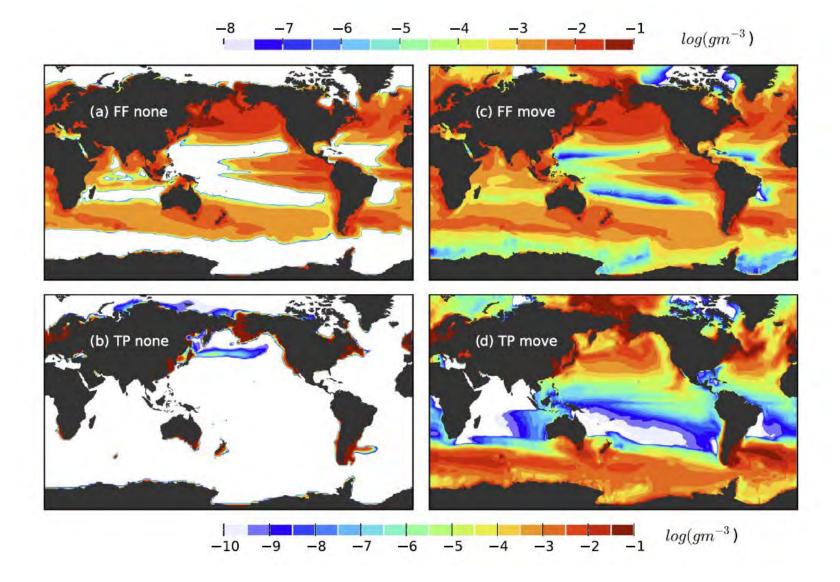
Reference	Publication year	Region	LME	Туре	# Specie	
Cheung et al.	2009	Global	NA	Retrospective and Projection		
Hollowed et al.	In press b	Arctic/Subarctic	Barents Sea, Bering Sea, Arctic	Vulnerability	17	
Huse and Ellingsen	2008	Arctic/Subarctic	Barents Sea	Retrospective and Projection	1	
Ciannelli and Bailey	2005	Subarctic	E. Bering Sea	Retrospective	1	
Mueter and Litzow	2008	Subarctic	E. Bering Sea	Retrospective	46	
Spencer	2008	Subarctic	E. Bering Sea	Retrospective	5	
Sundby and Nakken	2008	Subarctic	Norwegian Sea	Retrospective	1	
Drinkwater	2005	Subarctic	North Atlantic	Projection	1	
Drinkwater	2006	Subarctic	Northern North Atlantic	Retrospective	24	
Dulvy et al.	2008	Subarctic	North Sea	Retrospective	29	
Engelhard et al.	2011	Subarctic	North Sea	1913-2007	2	
Petitgas et al.	2012	Subarctic	North Sea	Retrospective	1	
Perry et al.	2005	Subarctic	North Sea	1977-2001	36	
Welch et al.	2001	Subarctic	North Pacific Ocean	Retrospective and Projection	1	
Tseng <i>et al.</i>	2011	Subarctic	Oyashio Current	Retrospective and Projection	1	
Fogarty et al.	2008	Temperate	NE US Continental Shelf	Retrospective and Projection	1	
Hare et al.	2012a	Temperate	NE US Continental Shelf	Projection	1	
Nye et al.	2009	Temperate	NE US Continental Shelf	Retrospective	36	
Hare et al.	2010	Temperate	NE US Continental Shelf	Retrospective and projection	1	
Last et al.	2011	Temperate	Australian Shelf	Retrospective	45	
Ito et al.	2010	Subarctic / Subtropical	Kuroshio/Oyashio current, Kuroshio Extension	Projection	1	
Okunishi et al.	2012	Subarctic / Subtropical	Kuroshio/Oyashio current, Kuroshio Extension	Projection	1	
Yatsu et al.	2013	Subtropical / Subtropical	Kuroshio/Oyashio current, Kuroshio Extension	Vulnerability	4	
Hare et al.	2012b	Subtropical	SE US Continental Shelf	Projection	1	
Agostini et al.	2008	Subtropical	California Current	Retrospective	1	
King et al.	2011	Subtropical	California Current	Vulnerability	8	
Hsieh et al.	2009	Subtropical	California Current	Retrospective	34	
Stewart et al.	2012	Subtropical	California Current	Retrospective	1	
Muhling et al.	2011	Tropical	Gulf of Mexico	Retrospective and Projection	1	
Su et al.	2011	Tropical	Pacific Ocean	Retrospective and Projection	1	
Lehodey et al.	2012	Tropical	Pacific Ocean	Retrospective and Projection	1	

Table 1. Recent studies of climate impacts on spatial distribution of marine fish and shellfish.

Hollowed et al. 2013. ICES Journal of Marine Science 70: 1023-1037.



Cheung et al. 2010. Global Change Biology 16: 24-35.



Watson et al. 2015. Progress in Oceanography 138: 521-532.

Progress: Movement Data

REVIEW SUMMARY

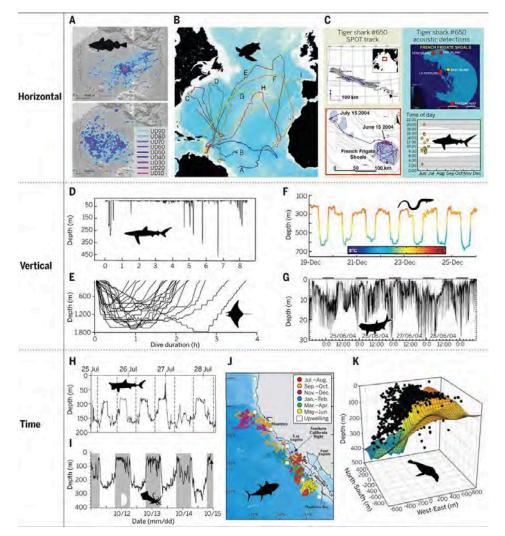
ECOLOGY

Aquatic animal telemetry: A panoramic window into the underwater world

Nigel E. Hussey, Steven T. Kessel, Kim Aarestrup, Steven J. Cooke, Paul D. Cowley, Aaron T. Fisk, Robert G. Harcourt, Kim N. Holland, Sara J. Iverson,* John F. Kocik, Joanna E. Mills Flemming, Fred G. Whoriskey

Science 348: 1255642, 2015

Fig. 2 Aquatic telemetry to understand the movements of animals in four dimensions: horizontal (2D), vertical (depth), and over time.

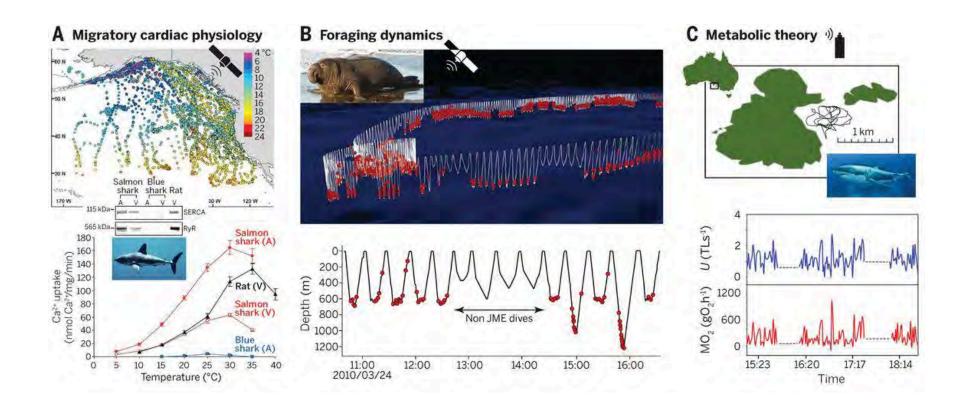


Nigel E. Hussey et al. Science 2015;348:1255642



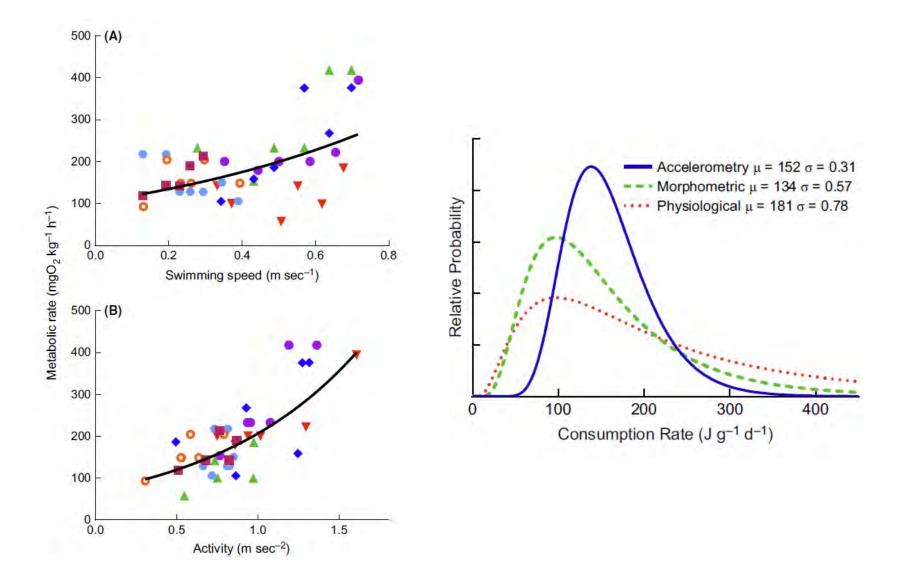
Published by AAAS

Top panel of Fig. 4 Multidisciplinary aquatic telemetry approaches.



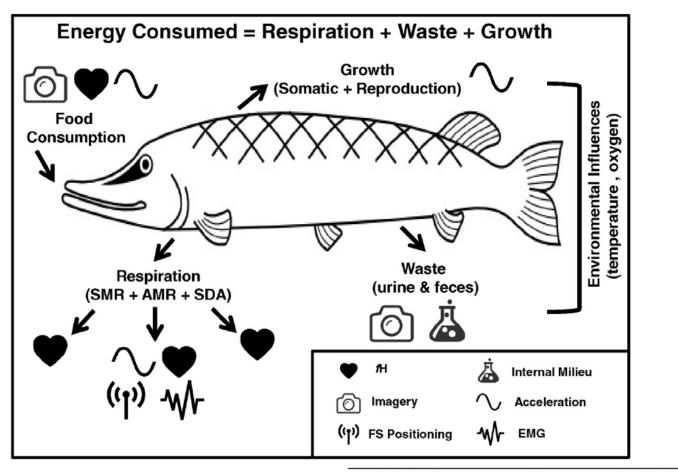
Nigel E. Hussey et al. Science 2015;348:1255642

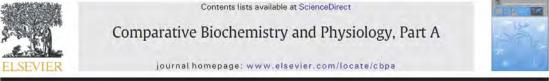




Brodie et al. 2016. Ecology and Evolution 6: 2262-2274.

11





Remote bioenergetics measurements in wild fish: Opportunities and challenges[†]

Steven J. Cooke ^{a,*}, Jacob W. Brownscombe ^a, Graham D. Raby ^b, Franziska Broell ^c, Scott G. Hinch ^d, Timothy D. Clark ^e, Jayson M. Semmens ^f

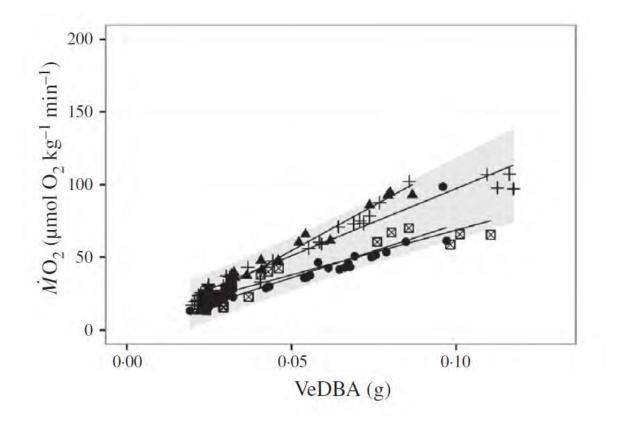
Device and/or	Year									
Sensor Type	1955	1965	1975	1985	1995	2005	2015	2025		
EMG transmitter (locomotion)										
EMG transmitter (opercular/mandibular)										
Acceleration logger										
Acceleration transmitter										
HR logger										
HR transmitter										
Positional telemetry (coarse-scale)										
Positional telemetry (fine-scale)										
Blood flow transmitter										
Imagery logger/transmitter										
Multiple Devices and/or Sensors										

Cooke et al. 2016. Comparative Biochemistry and Physiology A 202: 23-37.

Journal of Fish Biology (2016) **88**, 284–297 doi:10.1111/jfb.12804, available online at wileyonlinelibrary.com

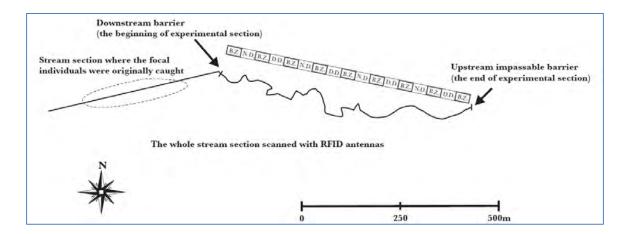
Recent advances in telemetry for estimating the energy metabolism of wild fishes

J. D. Metcalfe*[†], S. Wright^{*}[‡], C. Tudorache[§] and R. P. Wilson[‡]



Fish Personalities

... whereas environments with less predictable food abundance do not always meet costs of high activity and therefore passive or shy individuals can grow as fast as, or even faster than, active or bold individuals



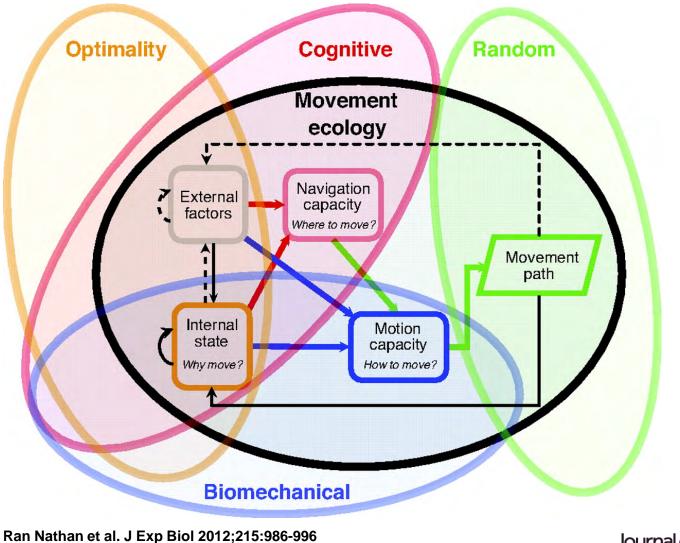
Zavorka et al. 2015. Behavioral Ecology 26: 877-884

Progress: Movement Modeling

- Many approaches have been proposed
 - $X(t+1) = X(t) + V_{x}(t)$
 - $Y(t+1) = Y(t) + V_y(t)$
 - $Z(t+1) = Z(t) + V_z(t)$
 - Determine the cell
- Quite confusing because of nonstandard descriptions and terminology for V_x, V_y, and V_z
 - Random walk
 - Run and tumble
 - Event-based
 - Restricted-area
 - Kinesis
 - ANN



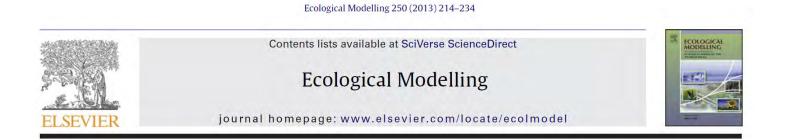
A movement ecology framework that integrates four existing paradigms for studying organismal movements.





Major Issue

 If we are to use these methods to simulate management actions and climate change, then the methods must predict responses to changes in cue(s)

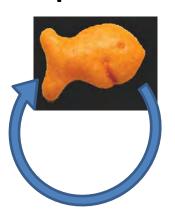


Evaluating the performance of individual-based animal movement models in novel environments

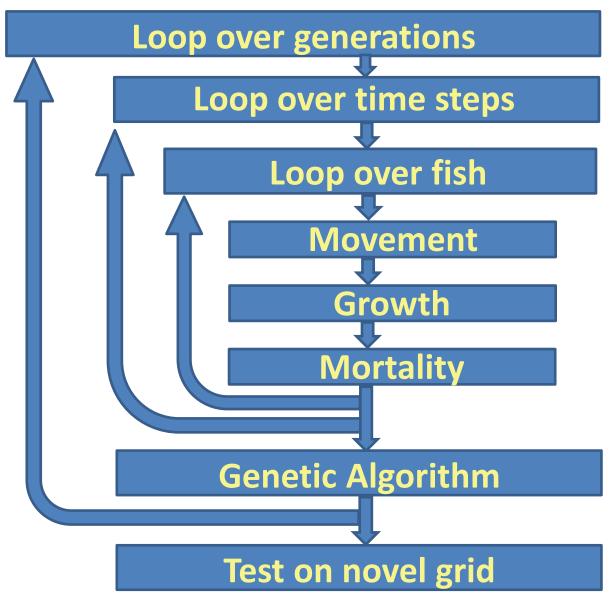
Katherine Shepard Watkins*, Kenneth A. Rose

Model Structure

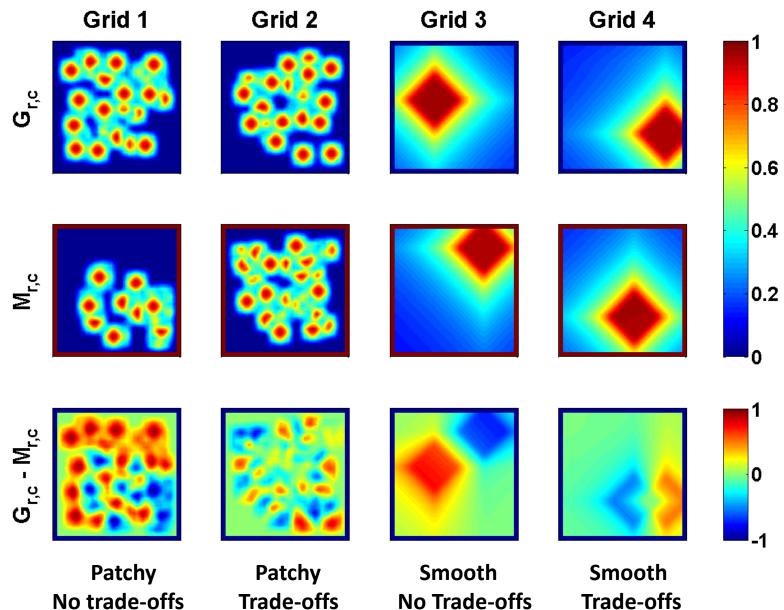
Simplified Hypothetical Species



Scale Grid: 540 x 540 cells Cells: 5 m² Time step: 5 minute Generation: 30 days Initial size = 73.3 mm Initial worth = 100 fish 3000 super-individuals



Environmental Gradients



Model Processes

Growth (mm 5-min⁻¹)

$$G = G_{max}^{*}G_{r,c}$$

L(t+1) = L(t) + G
W(t+1) = a*L(t+1)^b

Mortality (5-min)⁻¹

$$M = M_{max} * M_{r,c} * M_{L}$$

 $S(t+1) = S(t) * e^{-M}$
 $M_{L} = 1 - \frac{L_{i} - 73.3}{L_{max} - 73.3}$

$\frac{\text{Movement}}{X(t+1) = X(t) + V_x(t)}$ $Y(t+1) = Y(t) + V_y(t)$ cell location (r,c) Y or r 0,0 X and c

<u>Reproduction</u> E=55·S(30)·(421.84·W(30)+304.79)

GA Calibration

- 3000 strategy vectors of parameter values
 Start with random values for everyone
- Every 30-day generation, select 3000 individuals:
 - $P(selection) = E_i / \Sigma E$
 - Mutate each vector: 6% of parameters, ±0.25
- Use these 1000 vectors for the next generation
- Continue until egg production levels off
- Parameter values should have converged

Restricted Area Search

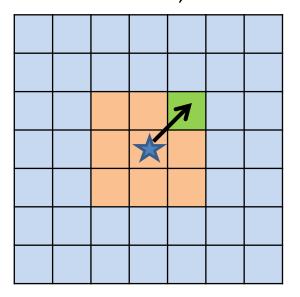
• Rank cells in a D_{hood} cell radius by habitat quality ($Q_{c,r}$) $Q_{c,r} = (1-\delta)^* (G_{c,r}+n) - \delta^* (M_{c,r}^*M_L+n)$

$$\circ n = \left(1 - \frac{1.42}{\sqrt{(c - xcell)^2 + (r - ycell)^2}}\right)$$

• Compute Θ = toward the cell with the highest $Q_{c,r}$

$$V_{x}(t) = (SS + RV_{1} \cdot R_{dist}) \cdot \cos(\theta + RV_{2} \cdot R_{\theta})$$
$$V_{y}(t) = (SS + RV_{1} \cdot R_{dist}) \cdot \sin(\theta + RV_{2} \cdot R_{\theta})$$

ο GA evolves: δ, R_{θ} , R_{dist} , D_{hood}



Kinesis – Robert Humston

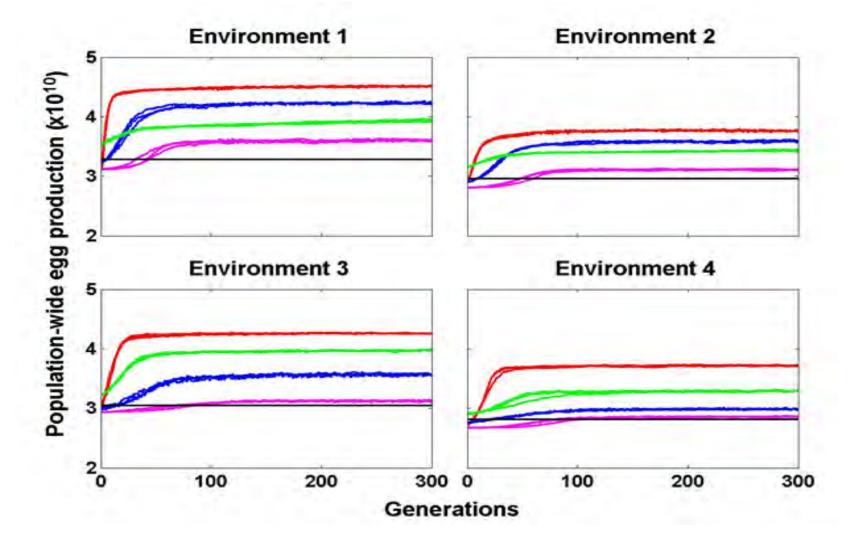
- Velocities are the sum of inertial (f) and random (g)
- Compute random swim speed: $\varepsilon_x = N(\sqrt{\frac{1.0}{2}, 0.5})$
- Compute habitat quality: $Q_{c,r} = (1-\delta) * G_{c,r} \delta * M_{c,r} * M_L$
- Compute f and g weighted by how close habitat quality (Q_{c,r}) is to the optimal habitat (Q_{opt})

$$f_{x} = \text{Vel}_{x}(t-1) \cdot \text{H}_{1} \cdot e^{-0.5\left(\frac{Q_{c,r}-Q_{opt}}{\sigma_{Q}}\right)^{2}}$$
$$g_{x} = \varepsilon_{x} \cdot \left(1 - \text{H}_{2} \cdot e^{-0.5\left(\frac{Q_{c,r}-Q_{opt}}{\sigma_{Q}}\right)^{2}}\right)$$

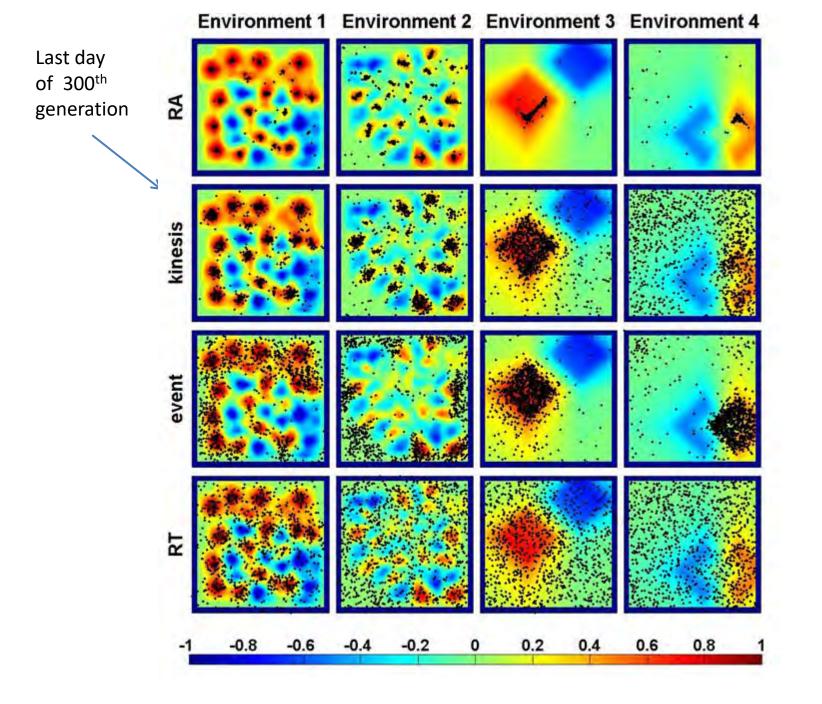
 $V_x(t) = f_x + g_x$ $V_y(t) = f_y + g_y$

ο GA evolves Q_{opt} , σ, H₁, H₂, δ

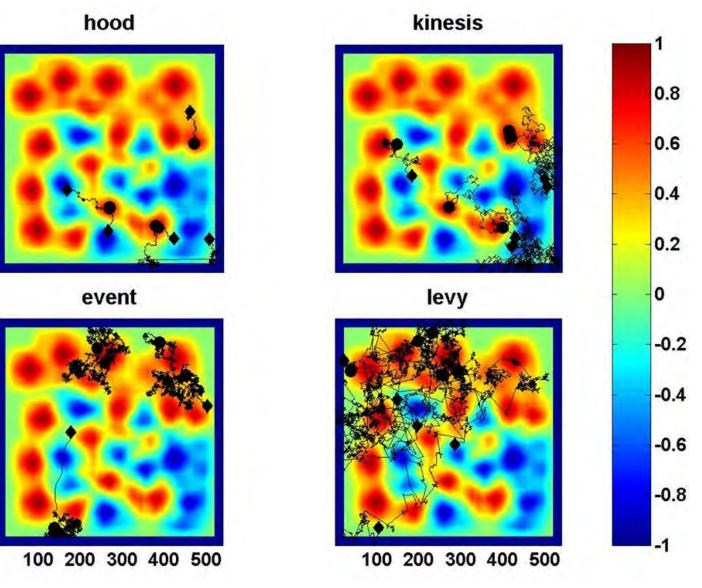
Calibration – Fitness Convergence



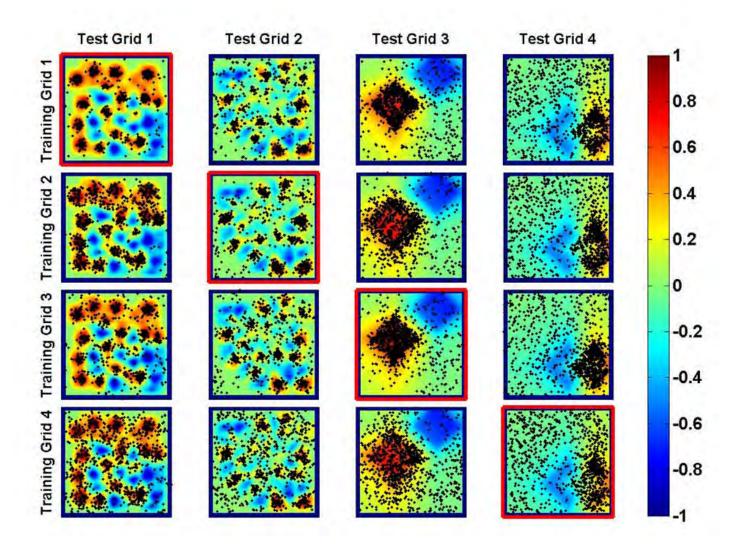
Restricted area, Kinesis, Event-based, Run-tumble



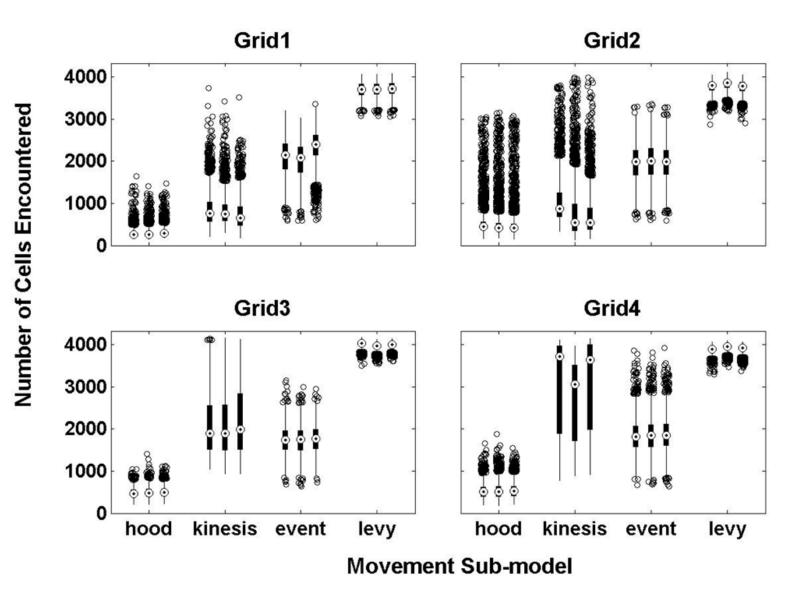
10 Individuals



Kinesis - Testing



Pathways



Enrique N. Curchitser Rutgers University

Jerome Fiechter University of California – Santa Cruz

Kate Hedstrom Institute of Marine Science - University of Alaska

Miguel Bernal FAO – Rome

Sean Creekmore Louisiana State University

Alan Haynie Alaska Fisheries Science Center - NOAA

Shin-ichi Ito University of Tokyo Bernard Megrey Alaska Fisheries Science Center - NOAA

Chris Edwards University of California – Santa Cruz

Dave Checkley Scripps Institute of Oceanography

Tony Koslow Scripps Institute – CALCOFI

Sam McClatchie Southwest Fisheries Science Center - NOAA

Francisco Werner Southwest Fisheries Science Center - NOAA

Alec MacCall Southwest Fisheries Science Center - NOAA

Vera Agostini Nature Conservancy

Rose et al. 2015. Demonstration of a fully-coupled end-to-end model for small pelagic fish using sardine and anchovy in the California Current. Progress in Oceanography 138: 348-380.

Fiechter et al. 2015. The role of environmental controls in determining sardine and anchovy population cycles in the California Current: Analysis of an end-to-end model. Progress in Oceanography 138: 381-398.

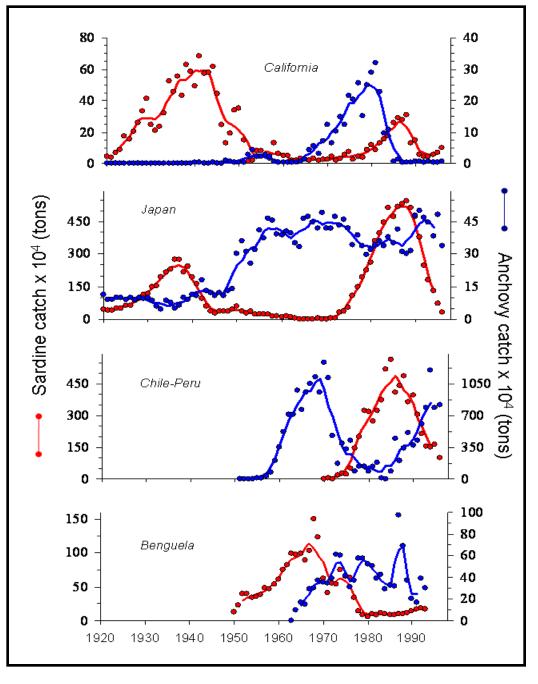






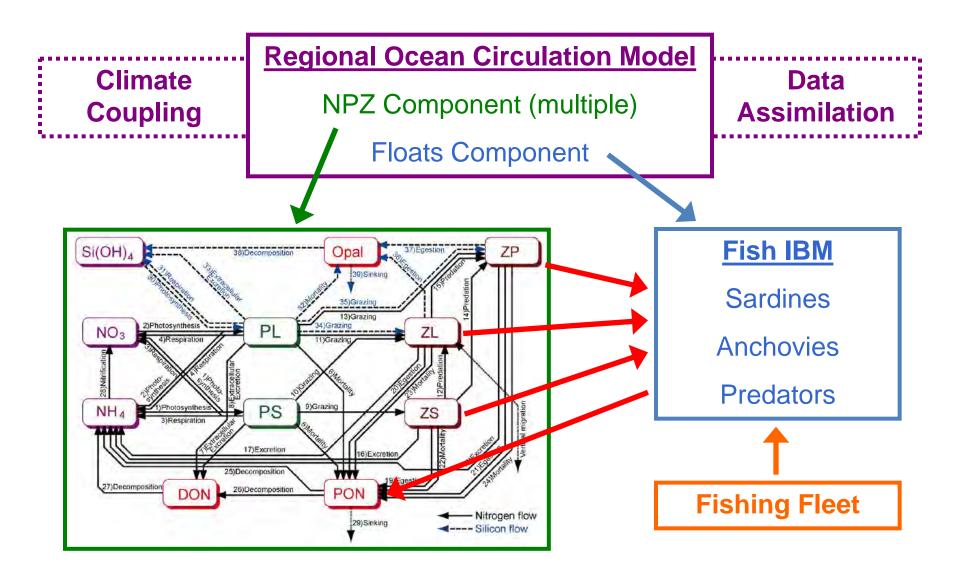






Provided by: Salvador E. Lluch-Cota based on Schwartzlose et al. 1999

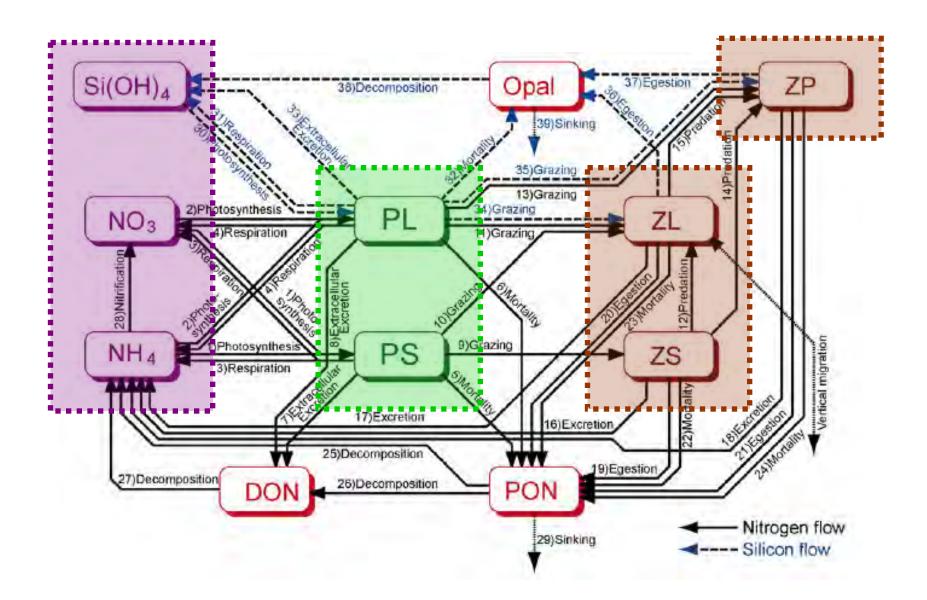
Fully-Coupled Model Within ROMS



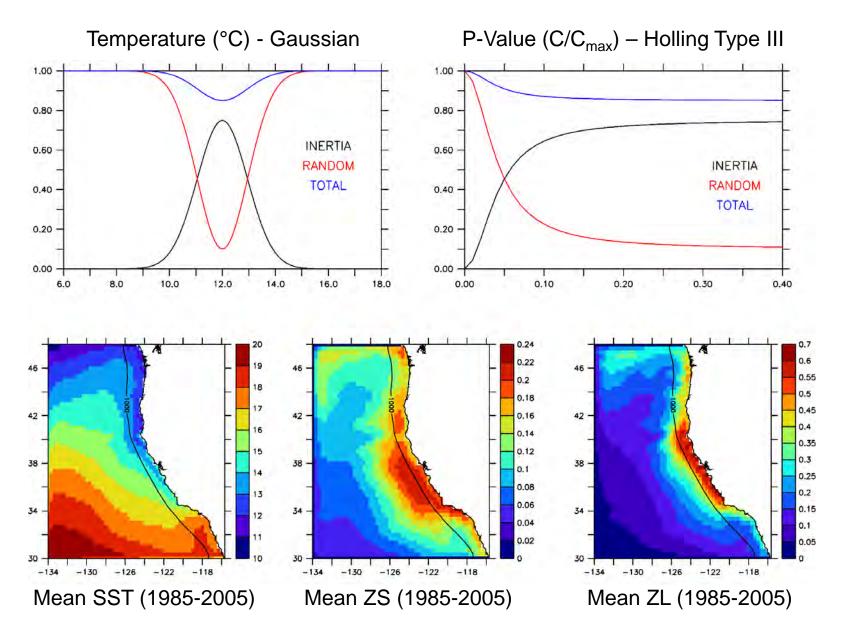
Model 1: ROMS 6000 1 • Grid: 5000 46°N -4000 -1000. 10 km 3000 42°N 2000 42 levels -2000. 1000 500 38°N -3000. 400 • 900 s 300 34°N -4000. 200 100 38°N 30°N 0 -5000 134°W 122°W -128.0-123.0130°W 126°W 118°W -127.0-126.0-125.0-124.0

• Run duration: 50 years (1959-2009)

Model 2: NEMURO

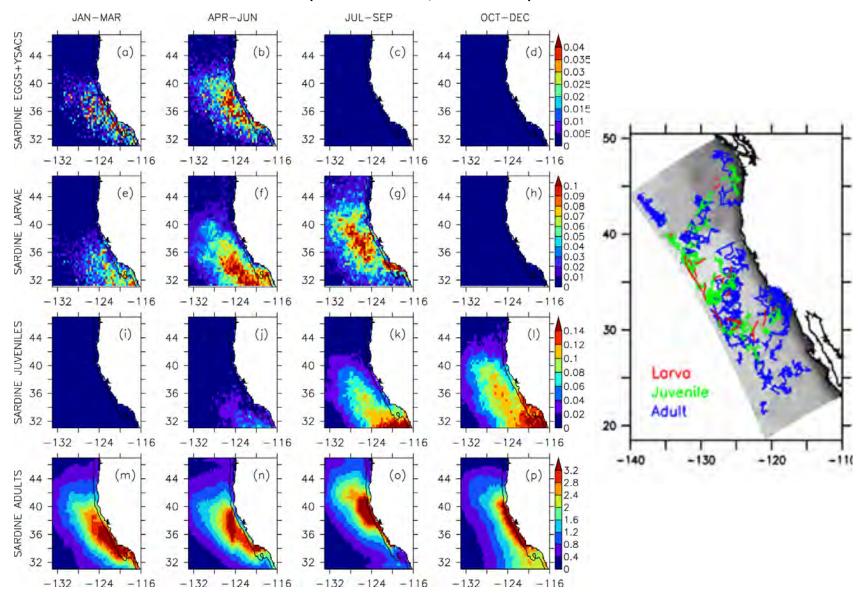


Environmental Cues for Movement (Kinesis)

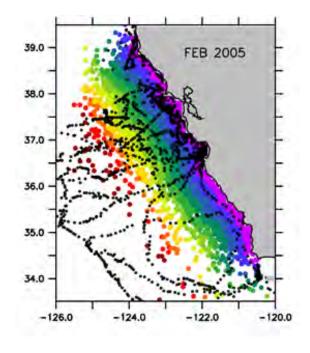


Sardine Spatial

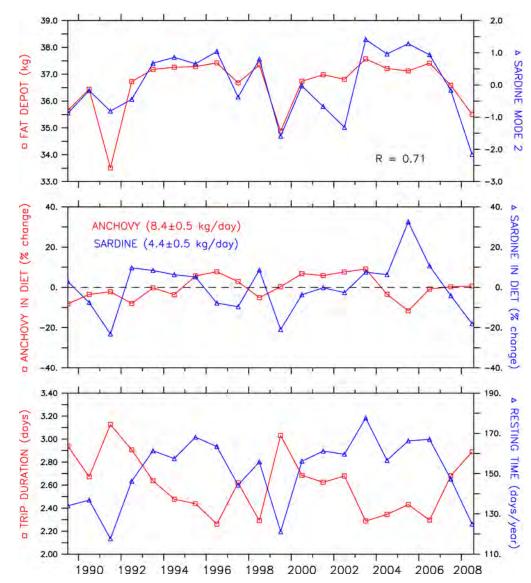
(E&YS - 10¹²; 1000 MT)



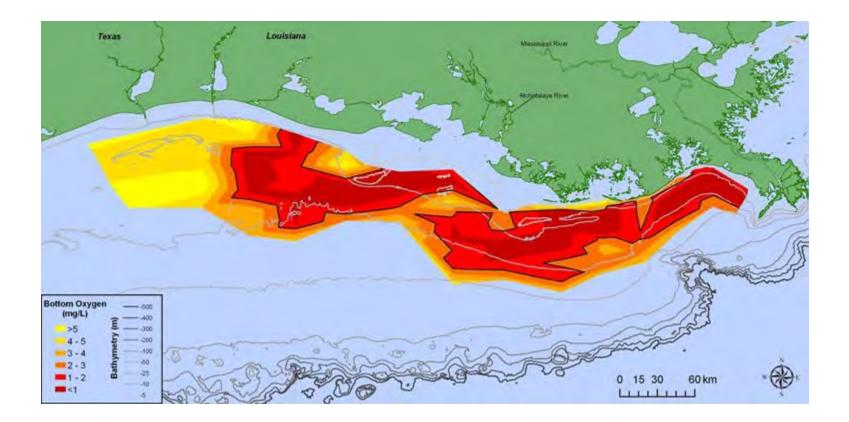
California Sea Lion



Fiechter et al. 2016. Marine Ecology Progress Series 556: 273-285.



Hypoxia - Gulf of Mexico





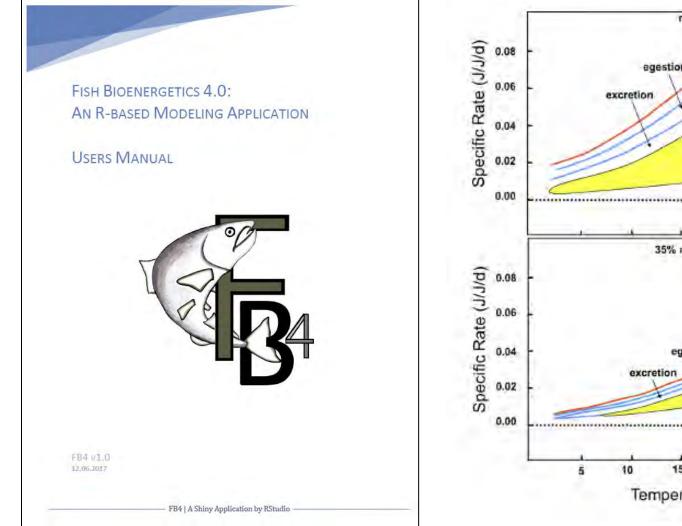
LaBone, E., D. Justic, K.A. Rose, and H. Huang. almost. Exposure of fish to hypoxia in the northern Gulf of Mexico: Effects of allowing fish to move vertically....

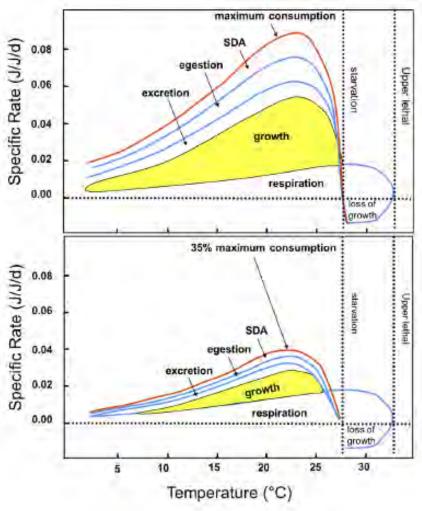
Bioenergetics

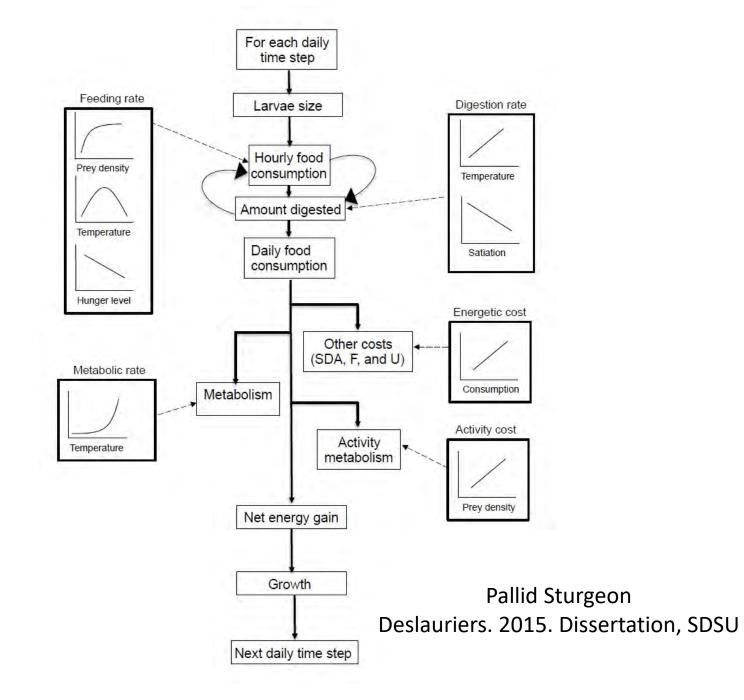
• Wisconsin formulation

• Dynamic Energy Budget

• Anchovy examples

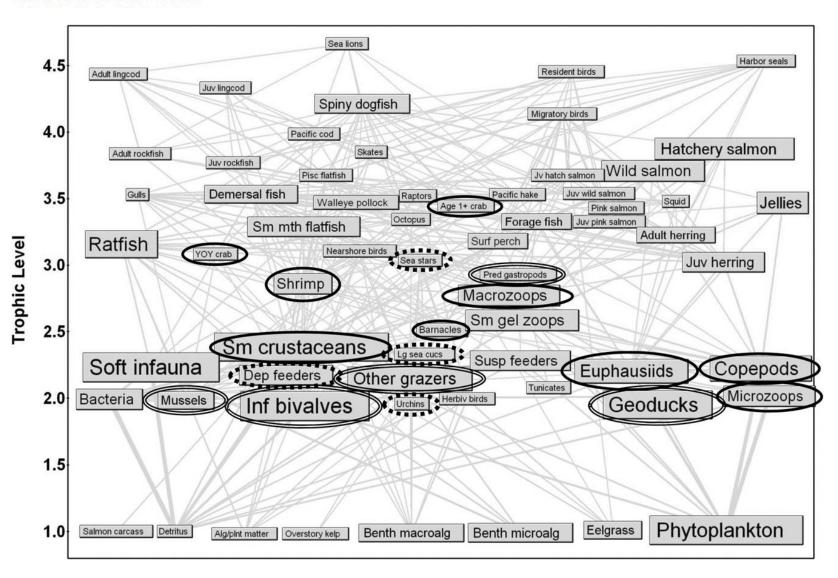


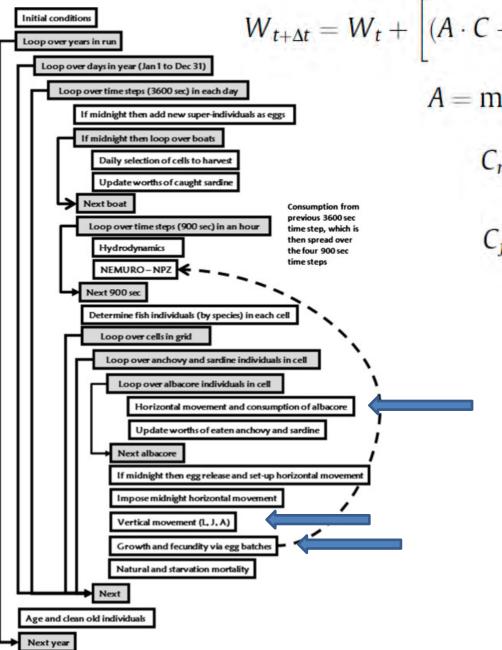






Busch et al. 2013. ICES Journal of Marine Science 70: 823-833.





$$C - R) \cdot W_t \cdot \left(\frac{e_f}{e_z}\right) - \frac{E}{e_f} \cdot \frac{\Delta t}{86,400}$$

$$\min(a_s \cdot W^{b_s}, A_M)$$

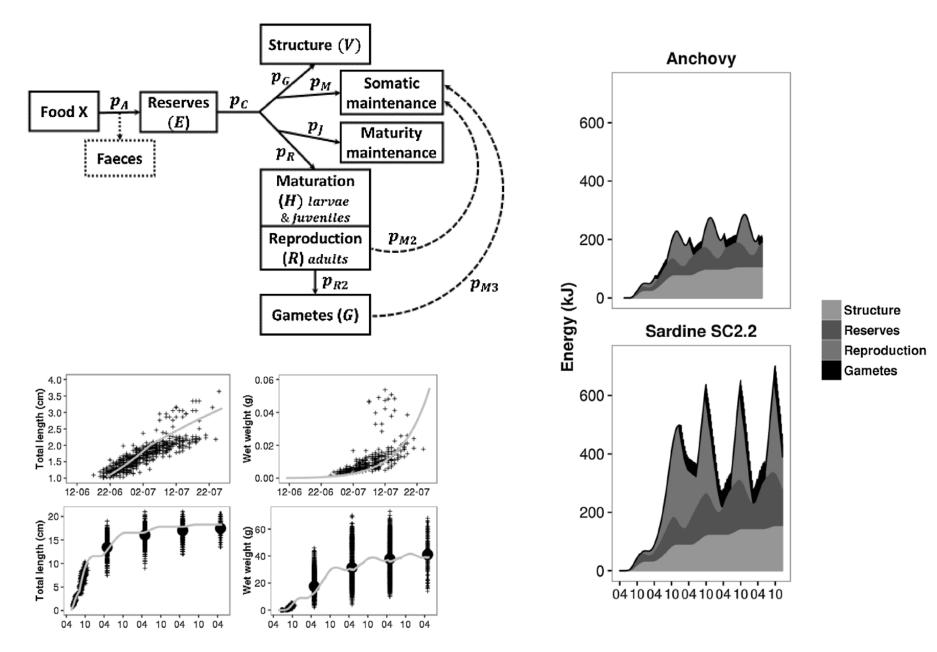
$$C_m = a_c W^{b_c} F(T)$$

$$C_j = \frac{C_m W\left(\frac{Z_j \cdot V_{sj}}{K_{sj}}\right)}{1 + \sum_{k=1}^3 \left(\frac{Z_k \cdot V_{sj}}{K_{sk}}\right)}$$

$$R = a_r W^{b_r} \cdot G(T) \cdot a_a \cdot 5.258$$

$$G(T) = e^{R_Q \cdot (T - T_r)}$$

$$a_a = e^{d_r * U_B * L/10}$$



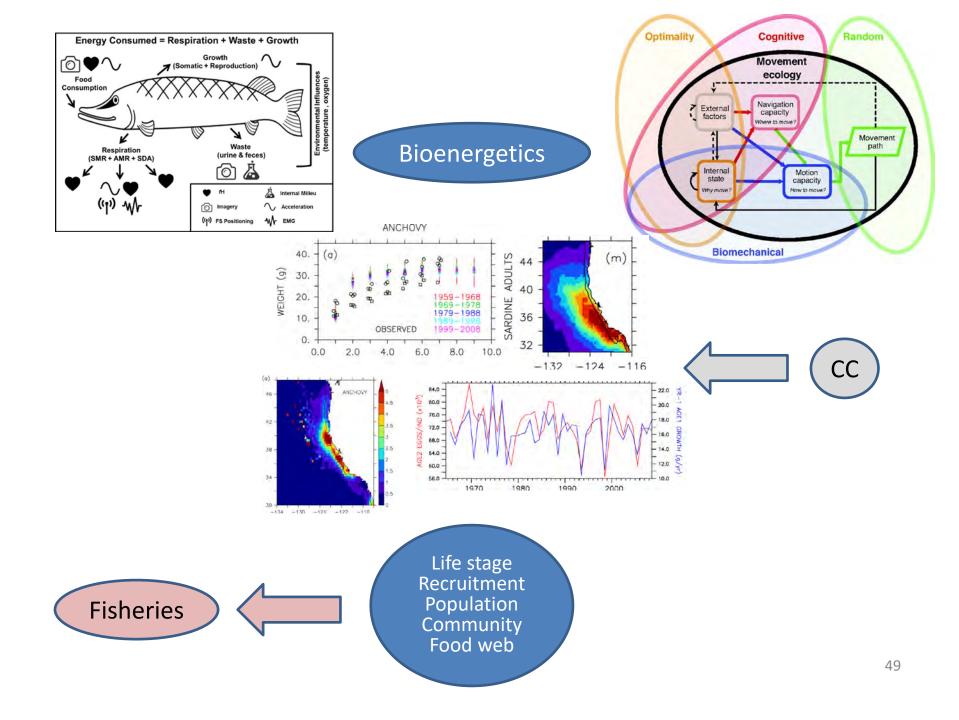
Gatti et al. 2017. Ecological Modelling 348: 93-109.

Disconnect

- Movement cues
 - Sometimes projected growth
 - Often temperature or other habitat variable
- Selection (optimization) of speed, direction, or destination
- Trajectory (journey)
- Bioenergetics consequences
- Routine type movement maybe OK but not for GCC

Necessity or Opportunity

- Merge movement with the bioenergetics
- Consistency (two-way)
- Journey and destination affect bioenergetics the same way as used in movement
- Project responses to major changes in cues



Next Step

- Time for synthesis and algorithm development and testing
- Working group or workshops?
- Fish and Fisheries ↔ Movement Ecology
- NOAA, PICES, ICES, ESA, AFS, CERF